

PLASMA FLYER – THE WORLD’S FIRST PLASMA FLOW CONTROLLED FLYING WING - model I

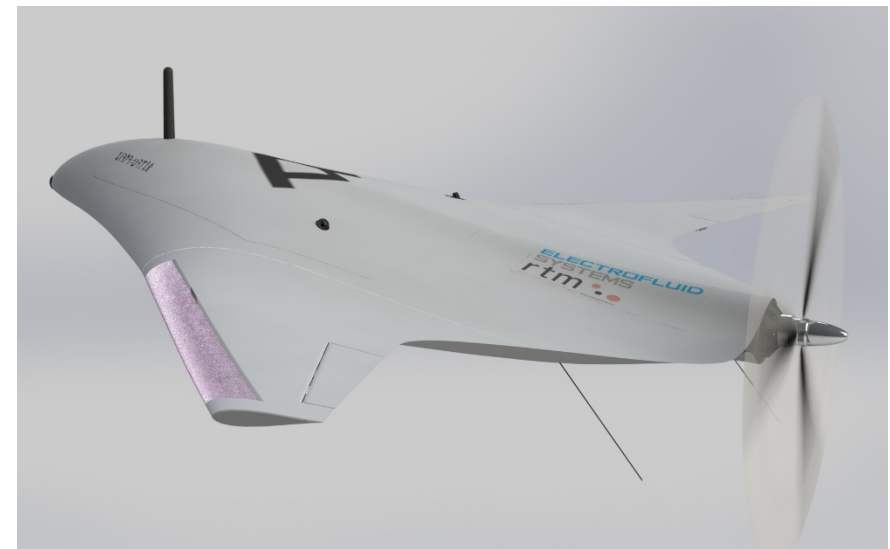


B. Göksel^{1,2}, I. Rechenberg², H. Klefenz³

¹Ingenieurbüro Göksel
Future Workshop
Electrofluidsystems
Voltastr. 1b, 13355 Berlin

²Department of Bionics
and Evolutionstechnique
Prof. Dr. Ingo Rechenberg
Technical University Berlin
Ackerstr. 71-76, 13355 Berlin

³RTM Resources+Technologies+Management
Dr. Heinrich Klefenz e.K.
Hauptstr. 35, 76879 Bornheim

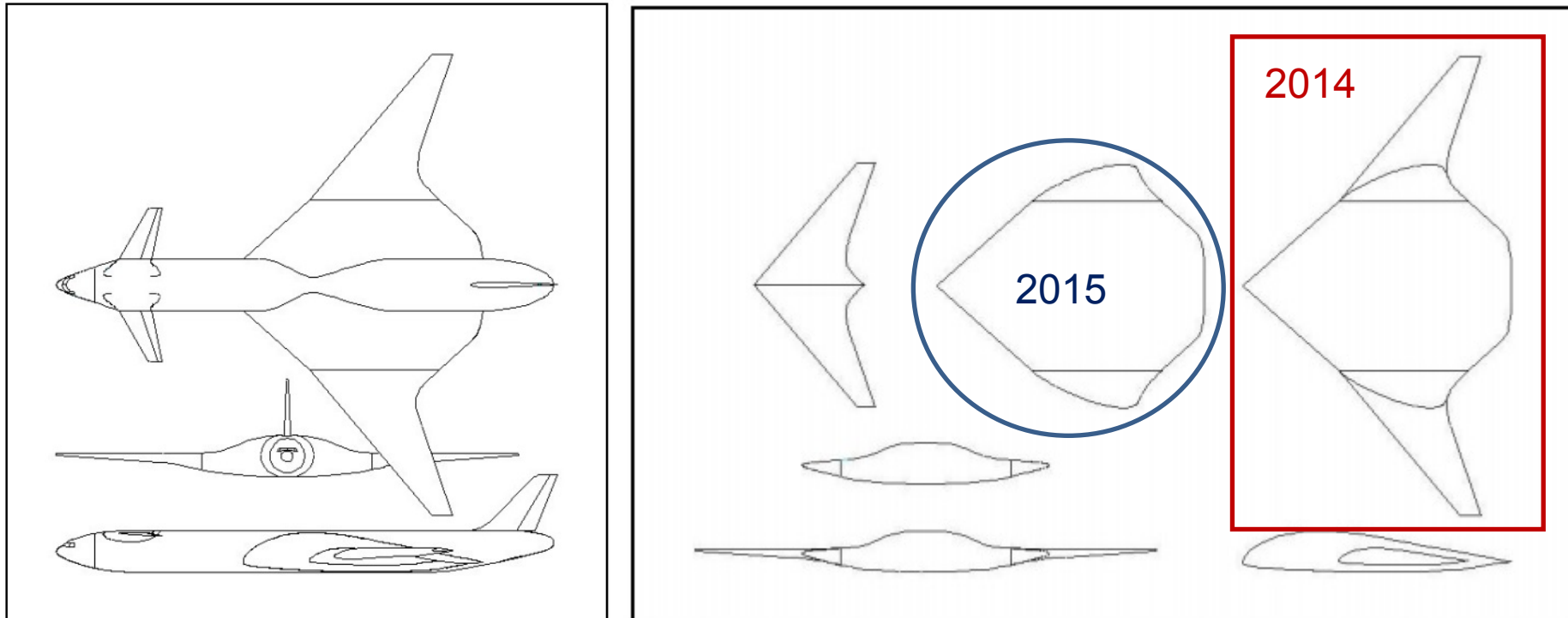


4th EASN Association International
Workshop on Flight Physics &
Aircraft Design
27th – 29th October 2014
RWTH Aachen University

- Motivation
- Experimental Setups
 - Flying Wing Airfoils
 - Flying Wing Half Models
 - Flying Wing Flight Models
- Discussion of Results
 - Airfoil Performance
 - Optimization Study
 - Half Wing Performance
- Conclusions and Outlook

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Motivated by Blended Wing and Hybrid Configurations from 1996 to 1998



Both pictures from my first publication at TU Berlin in 1998:



B. Göksel (1998) Studien zu einem bionischen Megaliner zukünftiger Generation. DGLR-JT98-19, Tagungsband I, Deutscher Luft- und Raumfahrtkongress 1998, Bremen, pp. 771-785.

Motivated by Blended Wing and Hybrid Configurations from 1996 to 1998



Extended design study with three students was honored with a reddot design award in 2008.

Motivated by Blended Wing and Hybrid Configurations from 1996 to 1998

 LIFTING AREA
 CABIN SPACE



Jumbo/Boeing 747

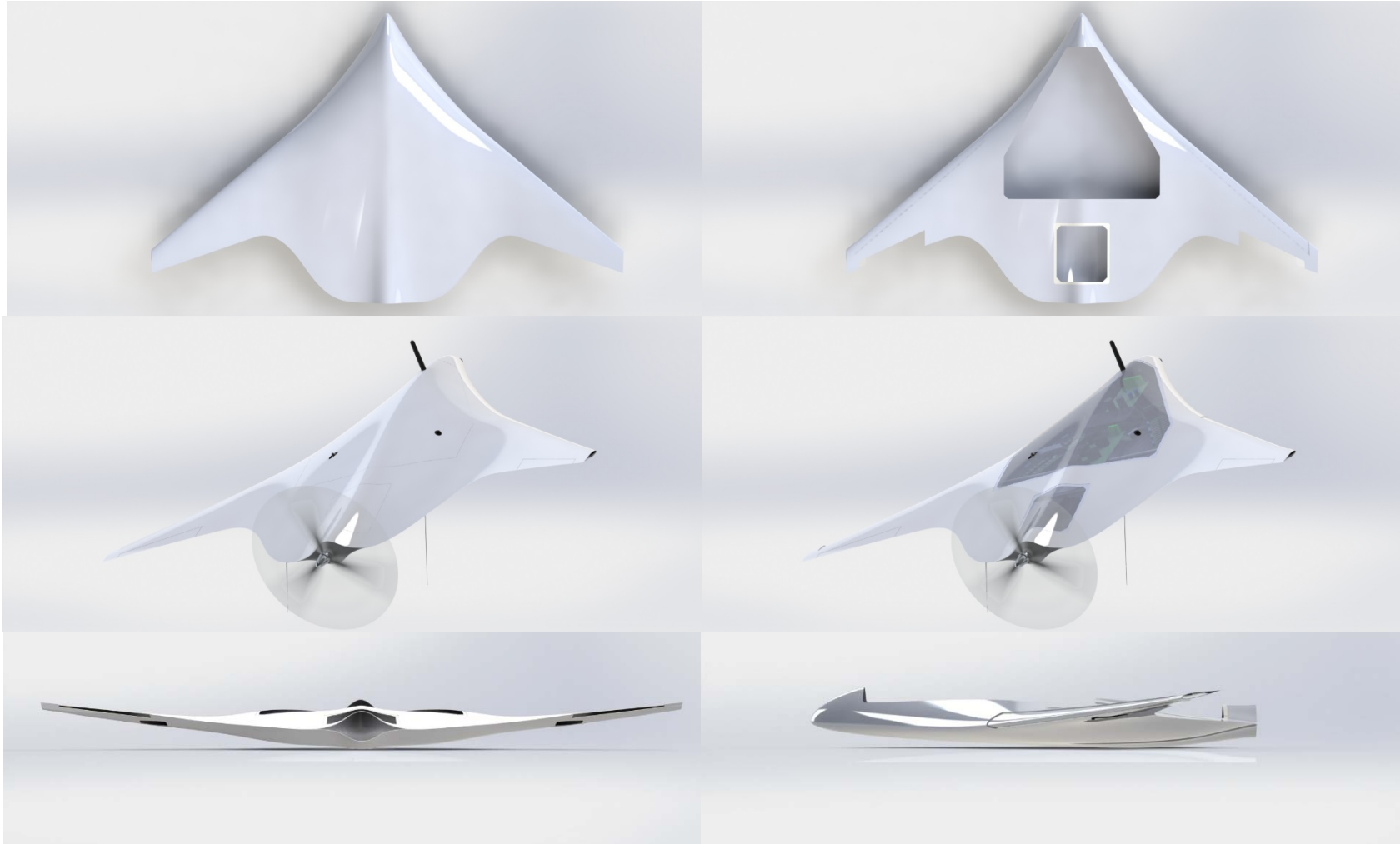


 streamliner

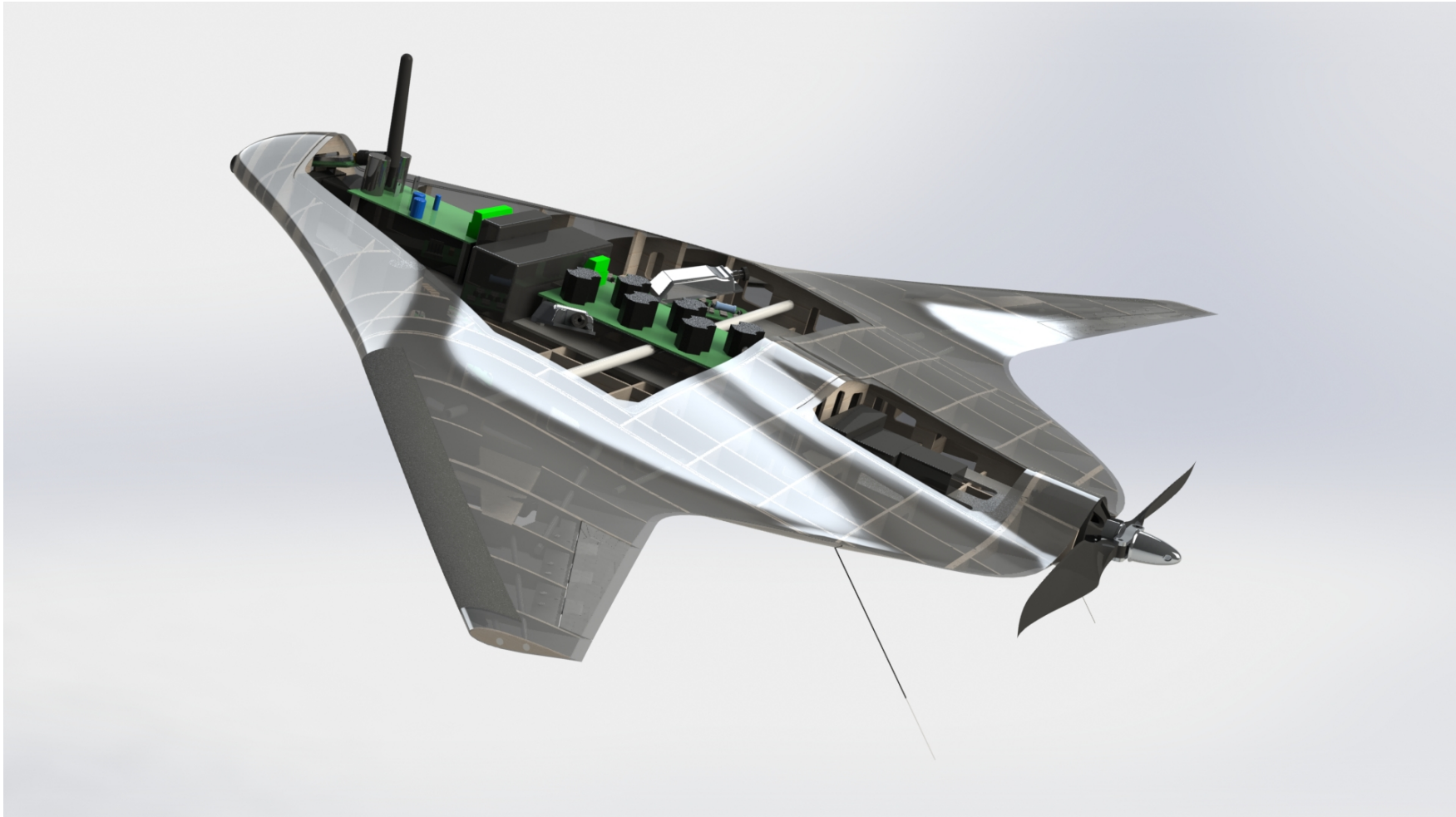


Nuplane Concept

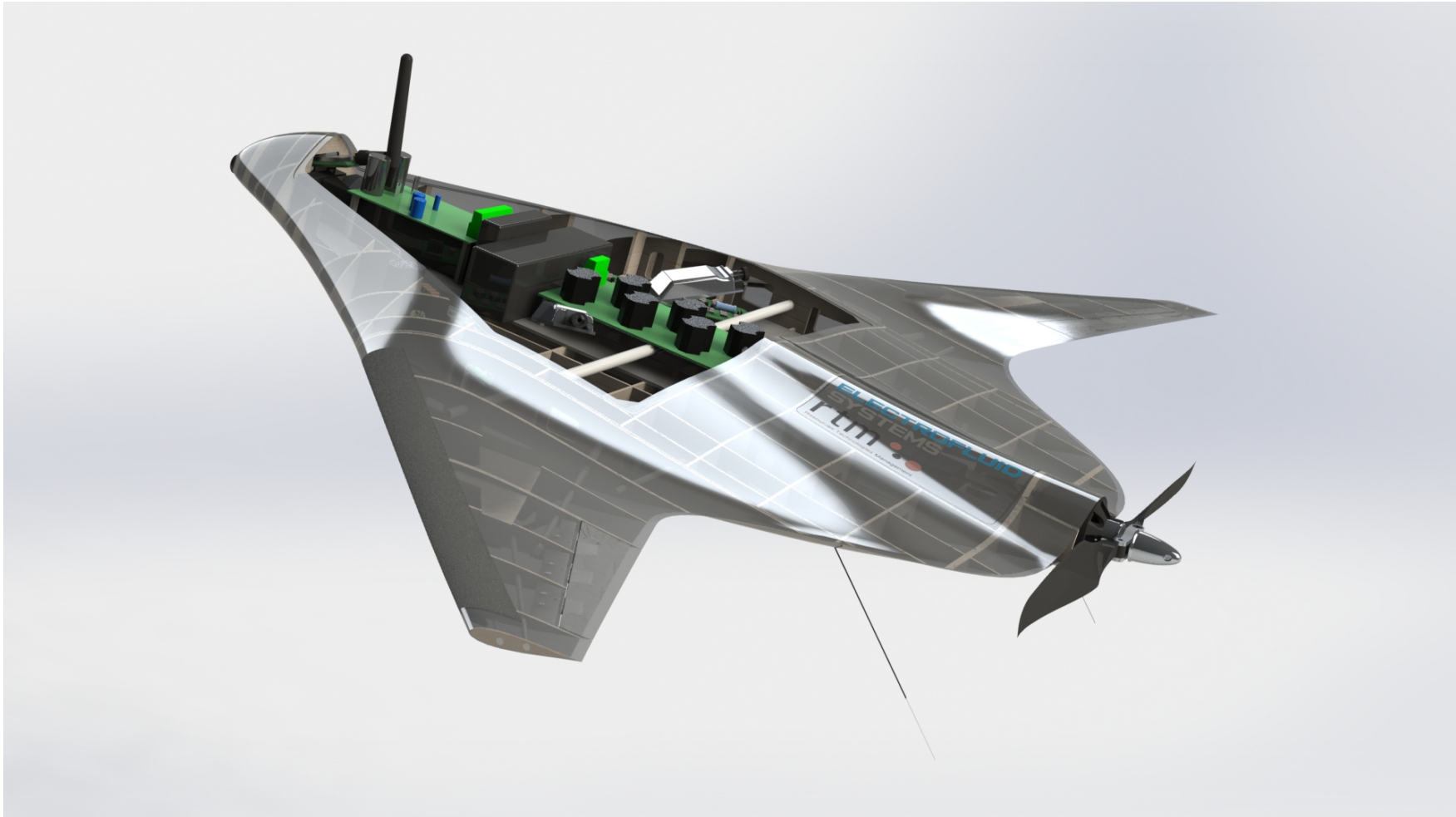
Motivated by Blended Wing and Hybrid Configurations in 1998



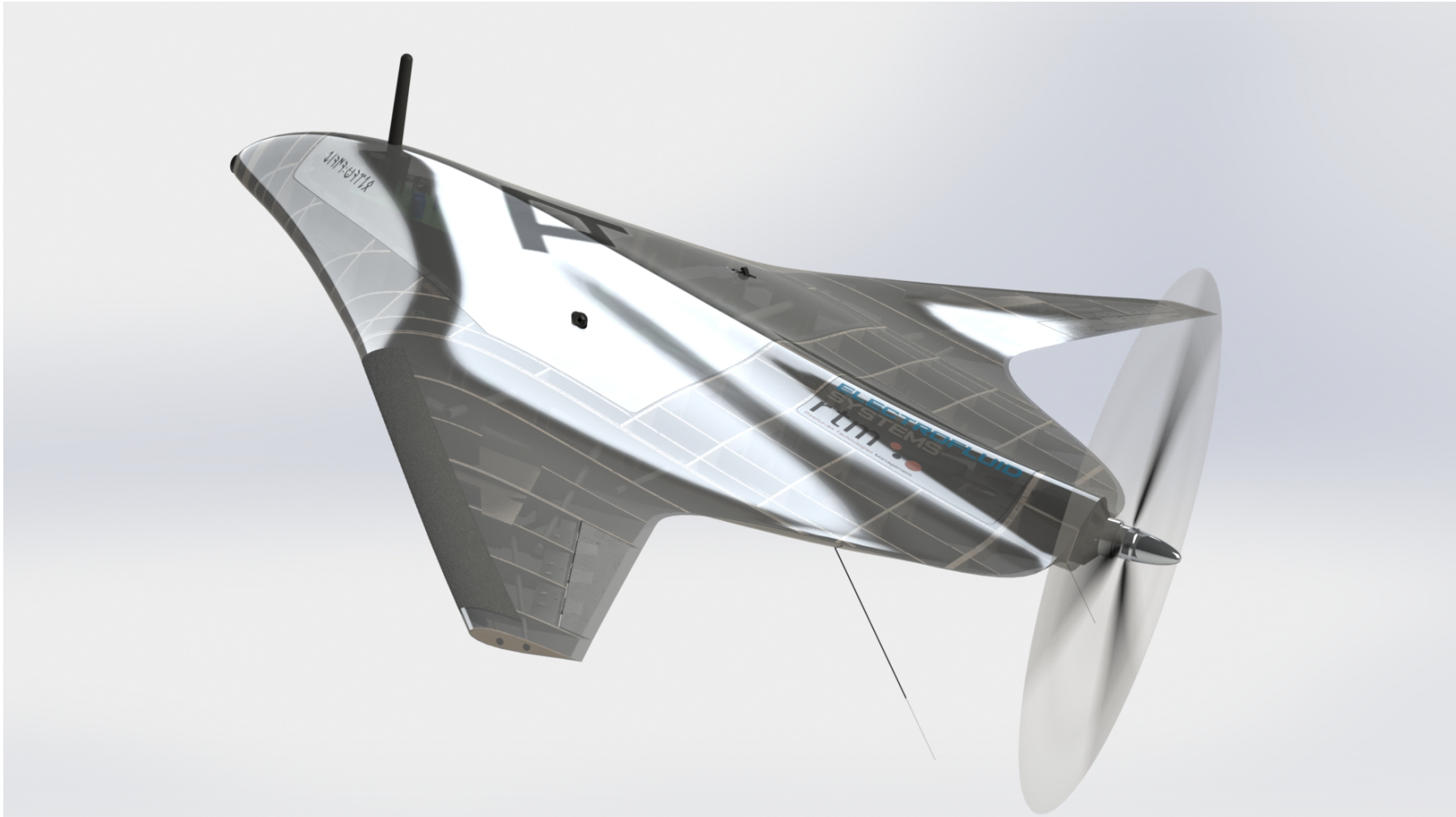
Motivated by Blended Wing and Hybrid Configurations in 1998



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Motivated by Blended Wing and Hybrid Configurations in 1998



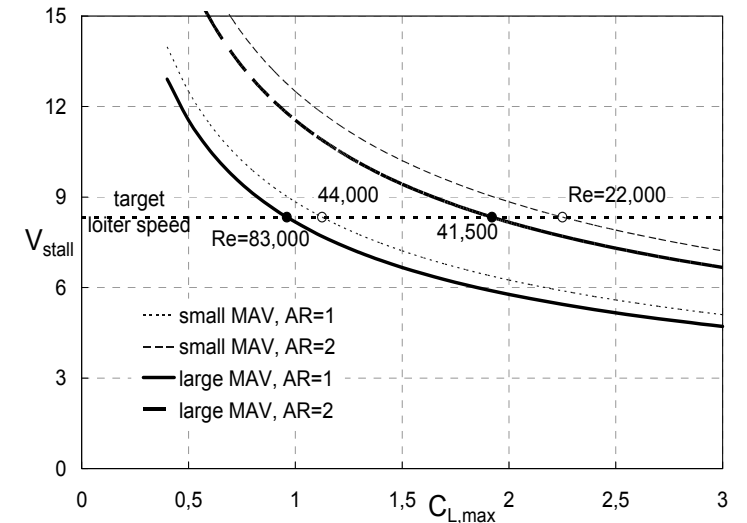
Motivation for Mini (<1.6m) and Micro UAVs (<0.8m)

Conventional Reynolds number UAVs (with $Re > 200,000$) achieve target loiter speeds by deploying flaps.

The generation of useful lift at $Re < 50,000$ is particularly challenging because passive tripping of the boundary layer is virtually impossible.

Without flow control low aspect ratio MAVs would have to fly almost ballistically to avoid stall at low speeds and low Reynolds numbers.

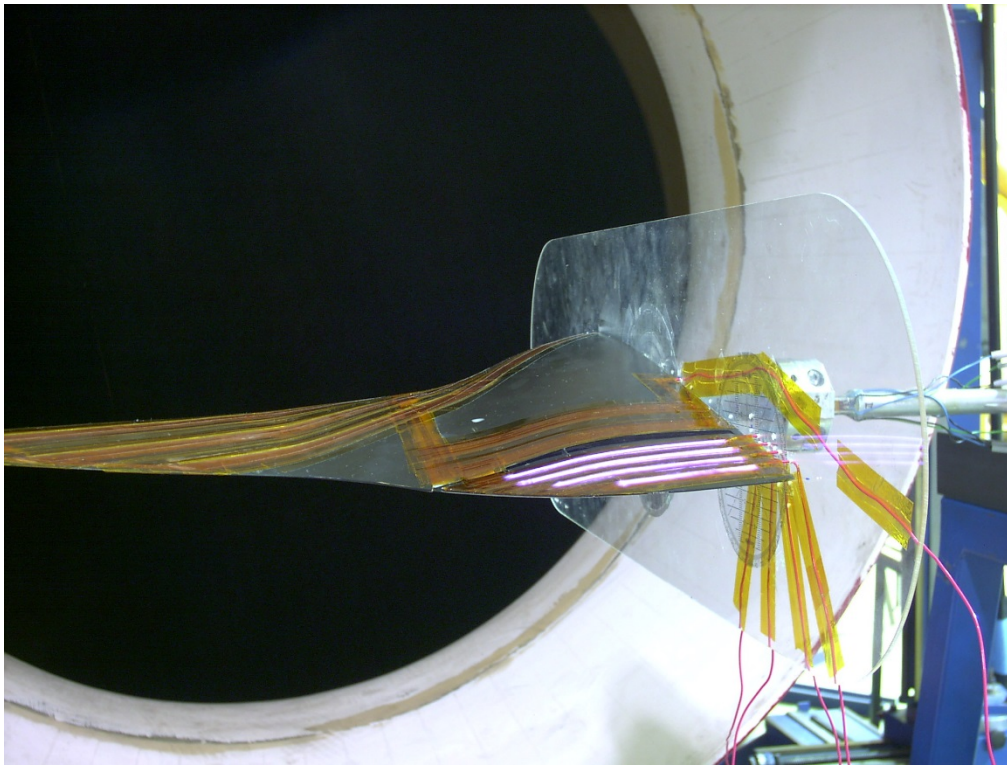
What can we do without flapping the wings?



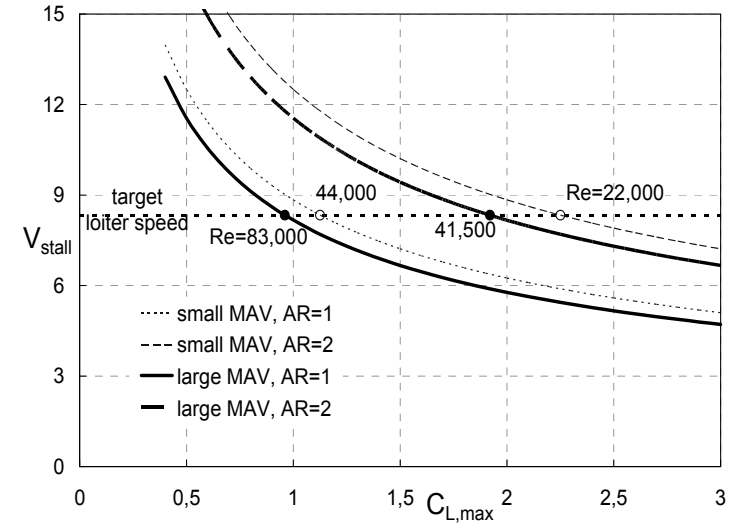
Stall speed as a function of maximum lift coefficient

Motivation for Mini (<1.6m) and Micro UAVs (<0.8m)

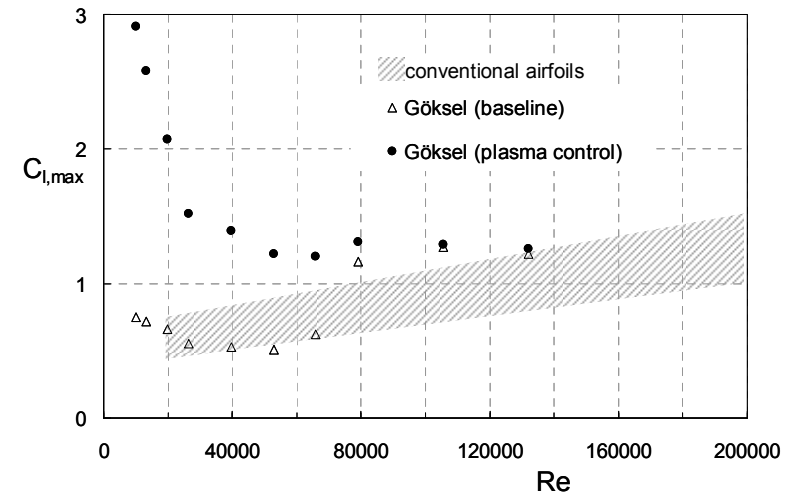
Flapping the fields! Pulsed plasma actuators could serve as plasma slats and plasma flaps for active separation and circulation control.



Let's Apply Plasma Flow and Plasma Roll Control on B-ionic Flying Wing Models



Stall speed as a function of maximum lift coefficient



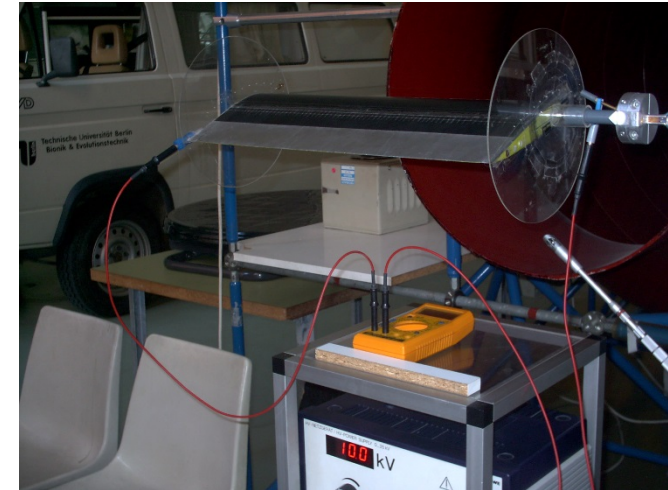
Plasma control data using corona discharges (~8.5 W)

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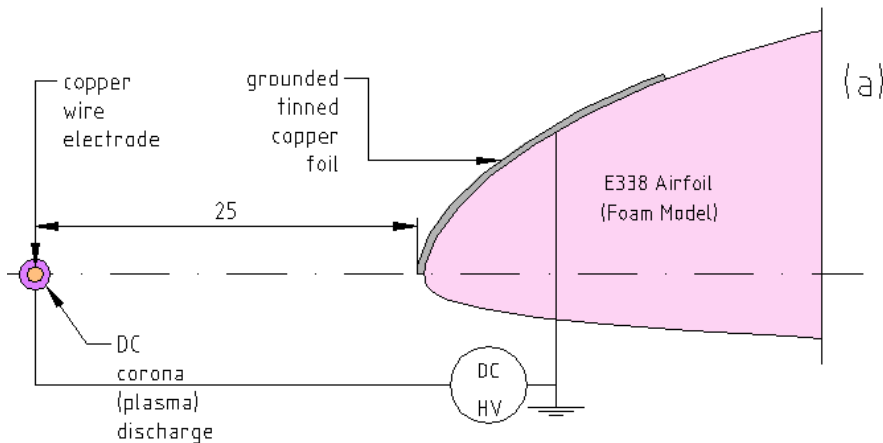
Eppler E338 Flying Wing Airfoils in Wind Tunnel

Tests Run at $20,000 \leq Re \leq 140,000$ (Airfoil)

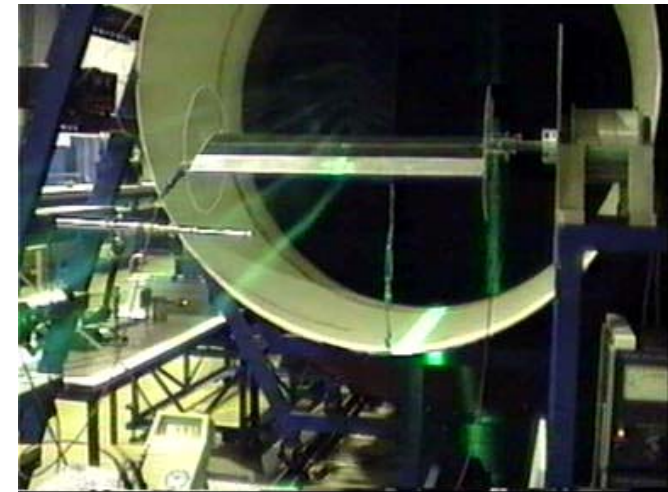
DC High Voltage (10 – 20 kV, 0.2 – 10 W)



$b=0.50$ m, $c=0.18$ m, $AR=2.8$



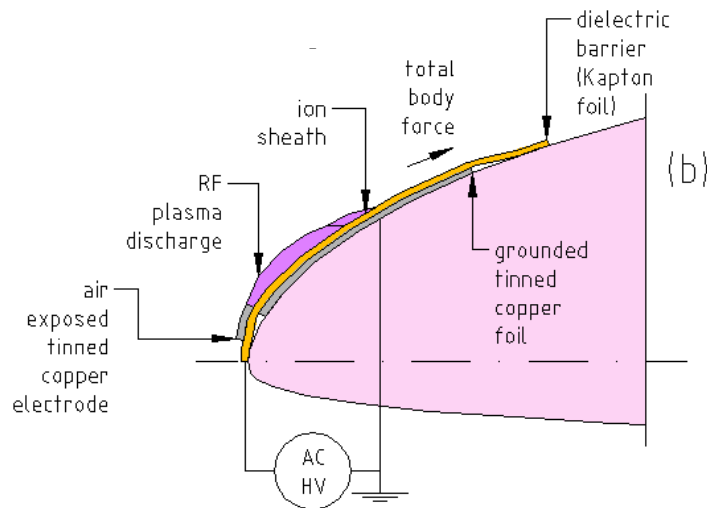
(a) Corona Discharge Plasma Actuator.



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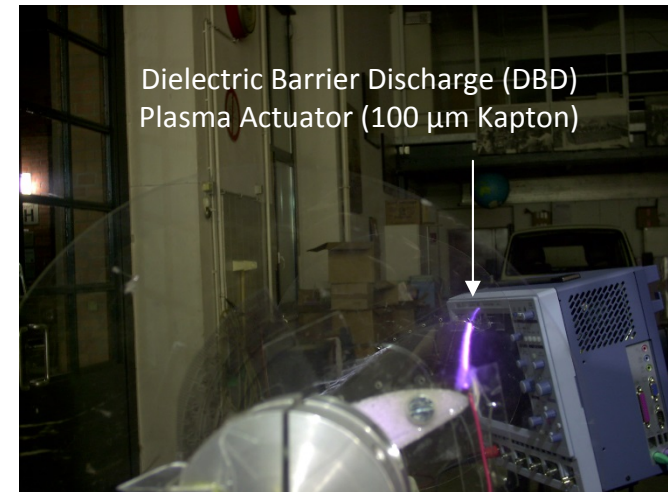
AC High Voltage (8 – 10 kVpp, 0.2 – 5.0 W)



(b) Dielectric Barrier Discharge Plasma Actuator.



$b=0.50$ m, $c=0.18$ m, $AR=2.8$

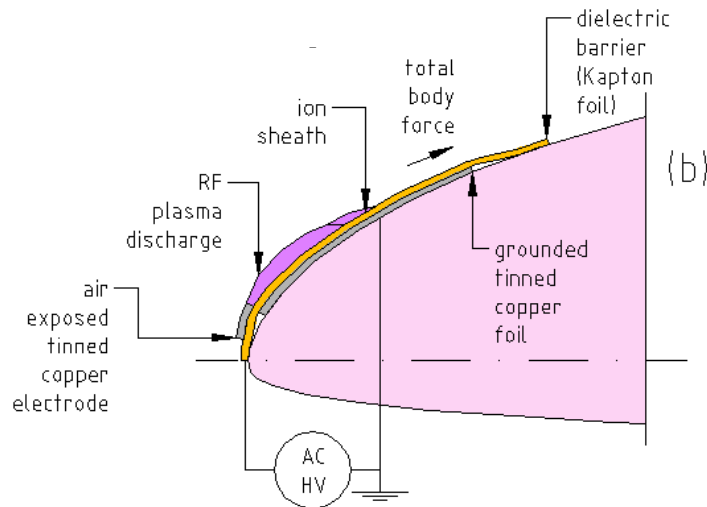


Dielectric Barrier Discharge (DBD)
 Plasma Actuator (100 μ m Kapton)

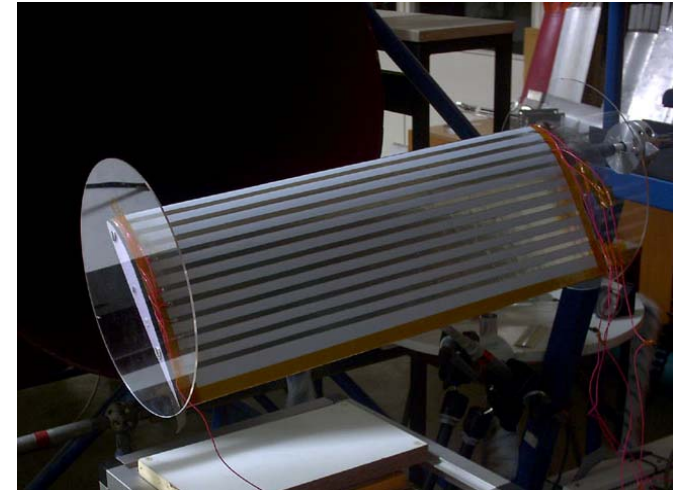
Eppler E338 Flying Wing Airfoils in Wind Tunnel

Tests Run at $20,000 \leq Re \leq 500,000$ (Airfoil)

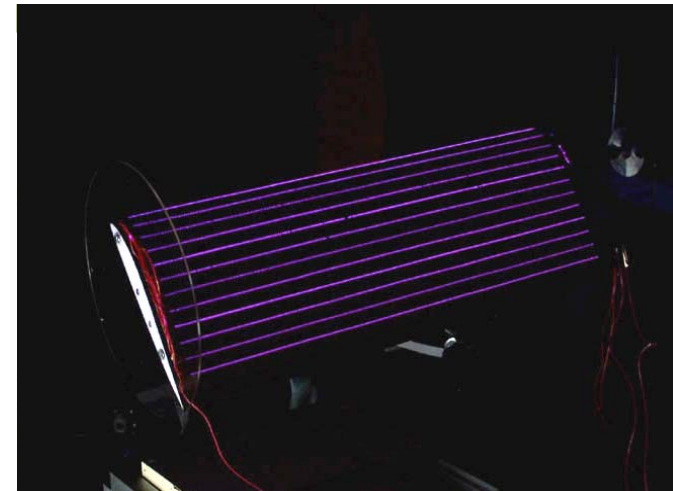
AC High Voltage (5 – 15 kVpp, 5.0 – 260 W)



(b) Dielectric Barrier Discharge (DBD) Plasma Actuator.



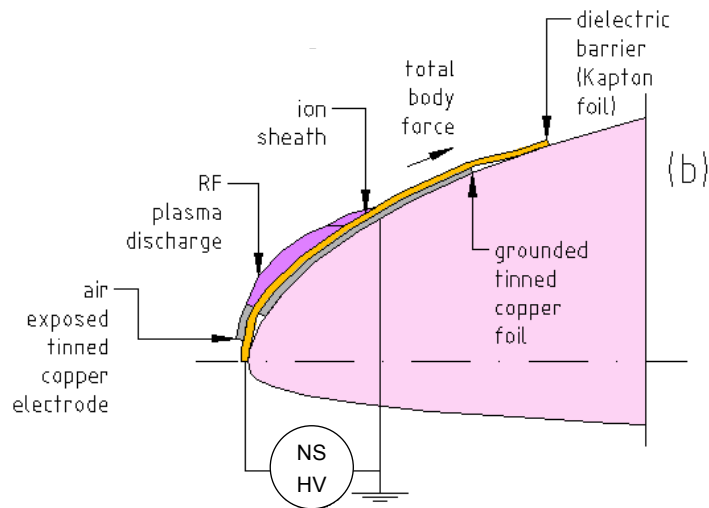
Multi DBD plasma actuators as phased array



Eppler E338 Flying Wing Airfoils in Wind Tunnel

Tests Run at $20,000 \leq Re \leq 500,000$ (Tube and 3D-Wing)

Nanosecond Pulsed High Voltage (5 – 25 kVp, 10 – 100 W)



(c) Nanosecond (NS) Pulse Driven DBD Plasma Actuator.



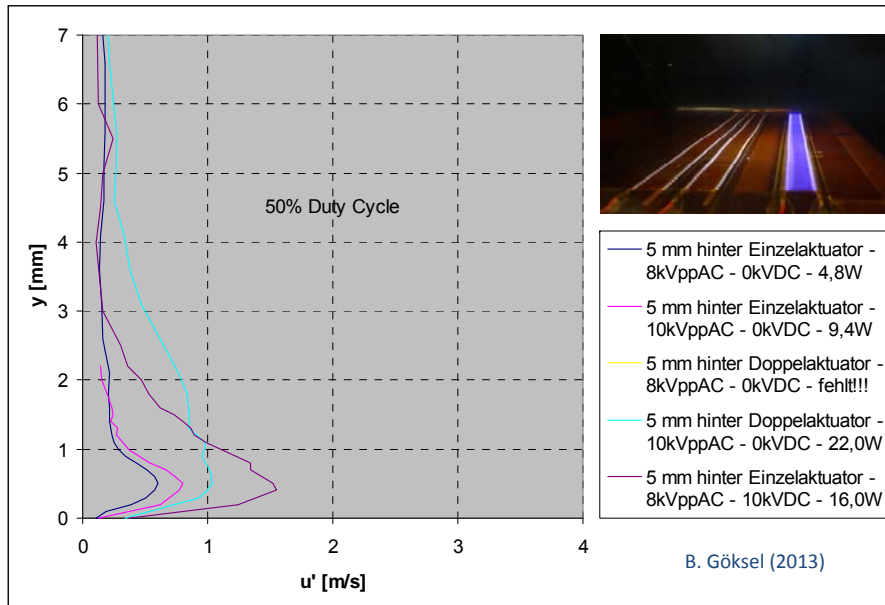
NS pulse driven ferroelectric cathode setup



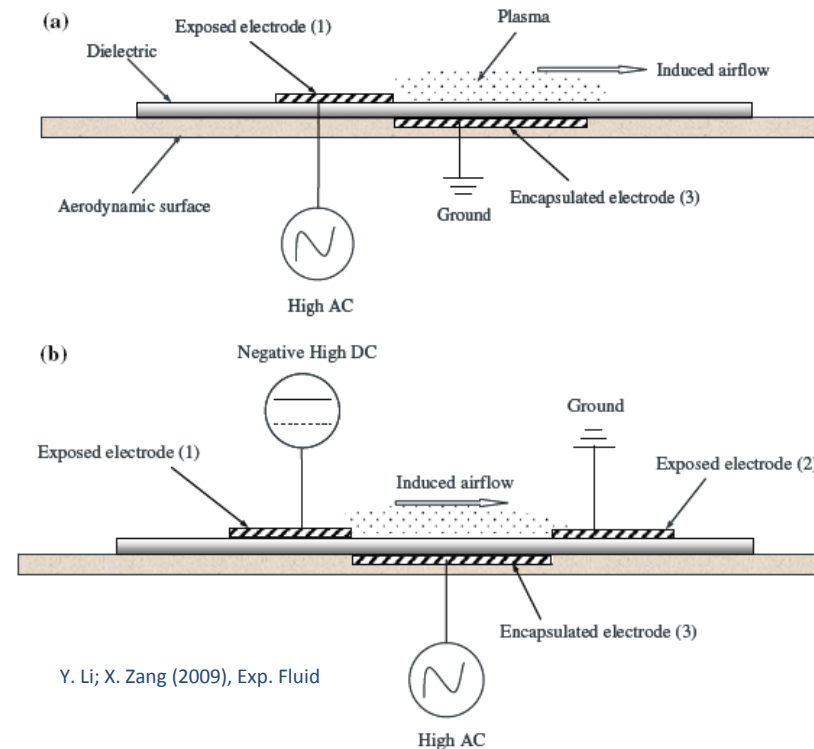
Eppler E338 Flying Wing Airfoils in Wind Tunnel

Tests Run at $50,000 \leq Re \leq 1,000,000$ (3D-Wing)

AC/NS High Voltage (5 – 30 kVpp, 5.0 – 100 W) &
 DC High Voltage (10 – 20 kVp, 10 – 60 W)



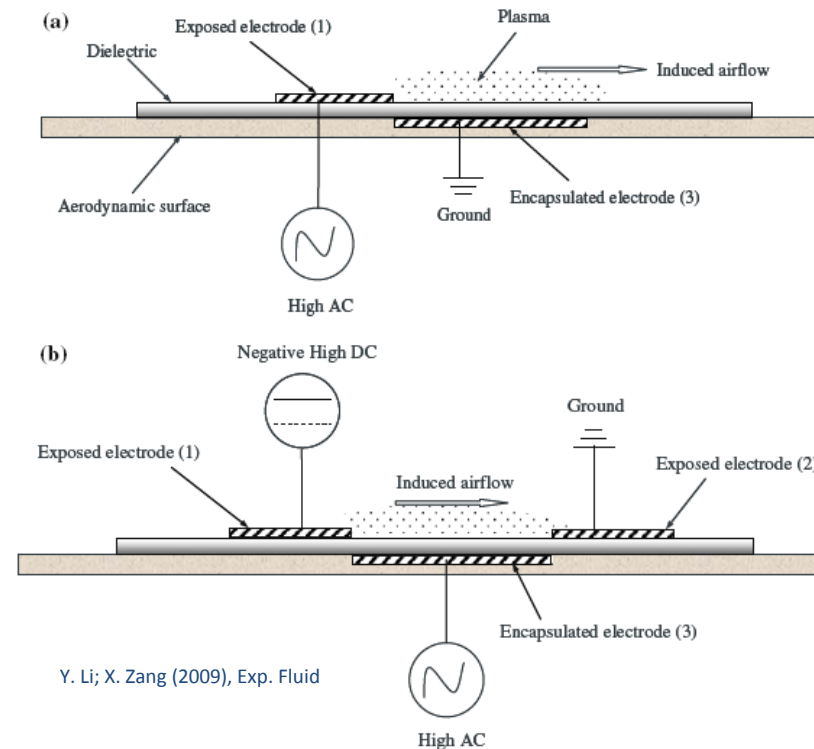
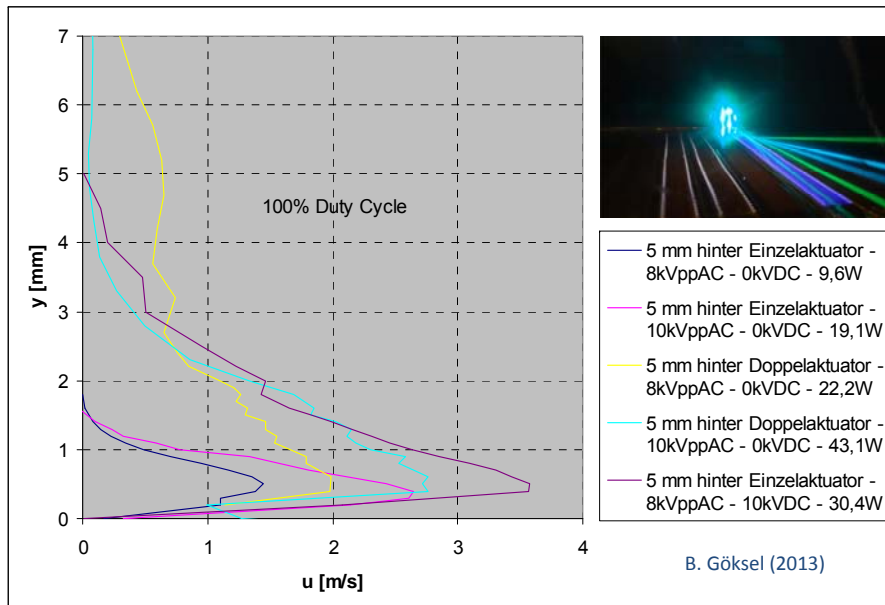
(d) Sliding Discharge Plasma Actuator.



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Tests Run at $50,000 \leq Re \leq 1,000,000$ (3D-Wing)

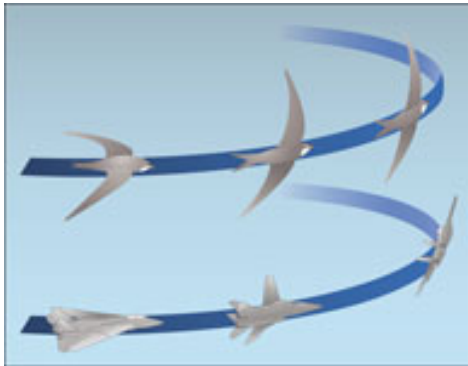
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(d) Sliding Discharge Plasma Actuator.

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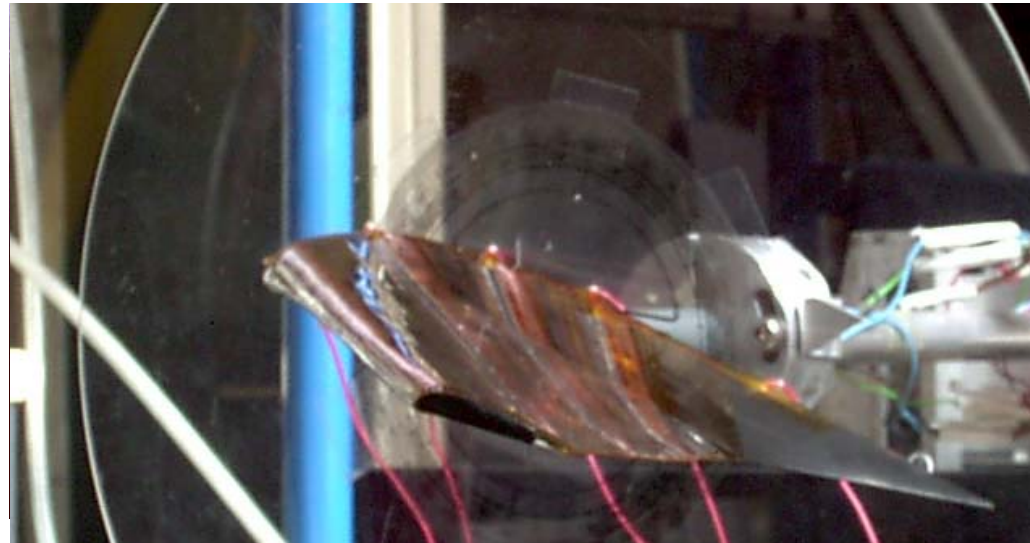
Eppler E338 Flying Wing Half Models in Wind Tunnel with 60 cm and 120 cm Diameter



Videler, J. J.; Stamhuis, E. J.; Povel, G. D. E. (2004)

 Leading-Edge Vortex Lifts Swifts. *Science* **306**

 (Dec 10), pp. 1960-1962.



Reynolds number distribution for MAV flying wing half-span (**38 cm**)

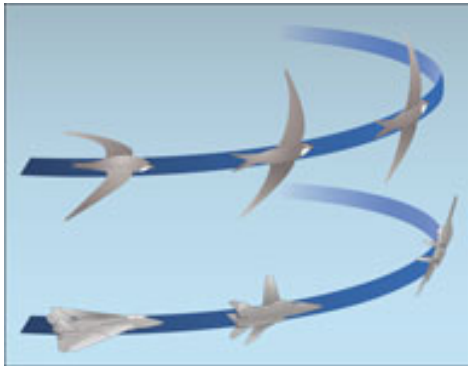
 wing model at typical cruise speed of 11.1 m/s (40 km/h, 25 mph).

$\alpha = 0^\circ$



$b=0.39\text{ m}, c=0.48\text{ m}, AR=2.0$

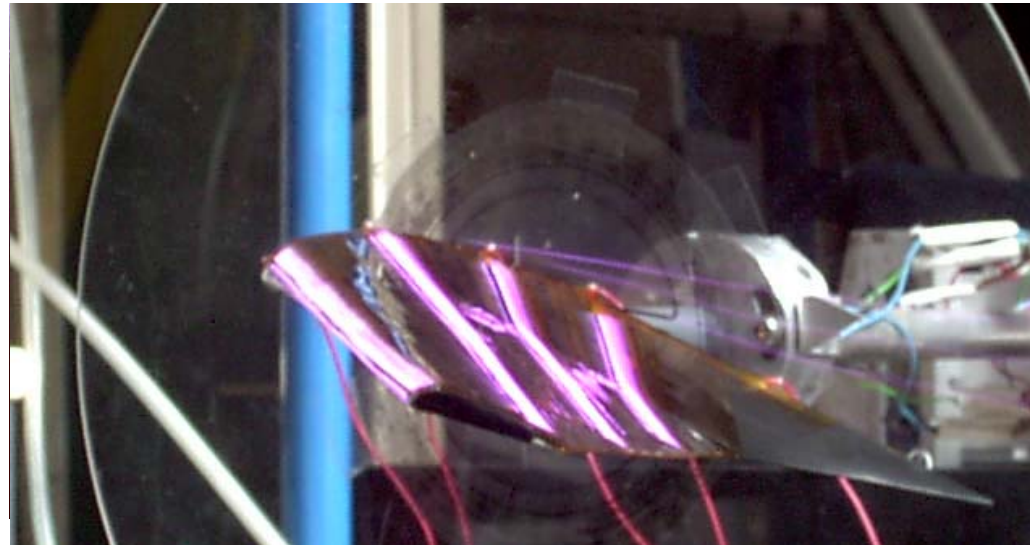
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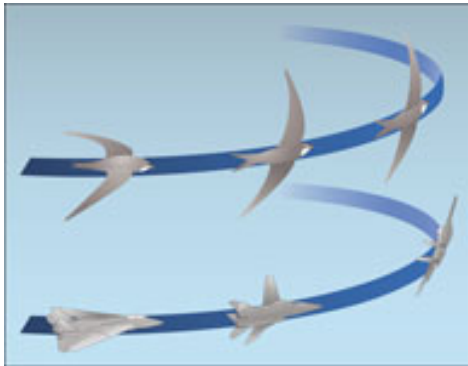
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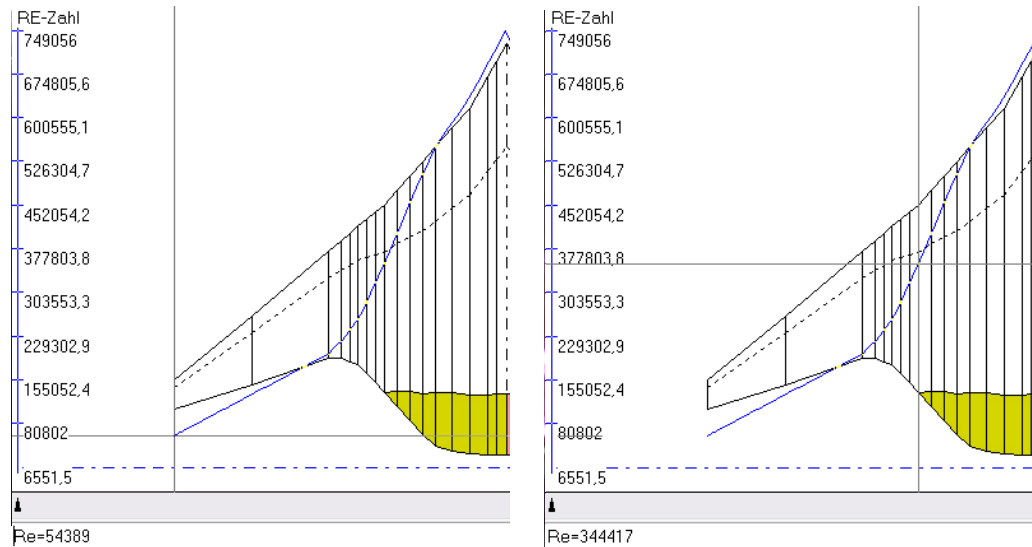
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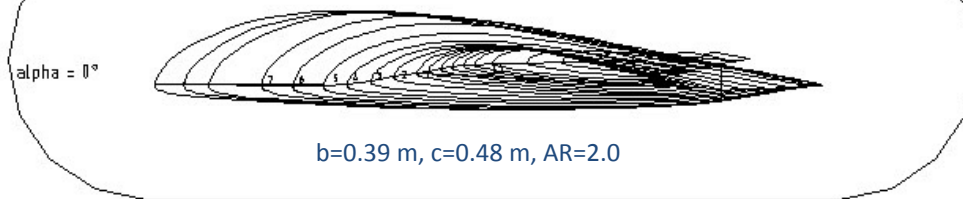
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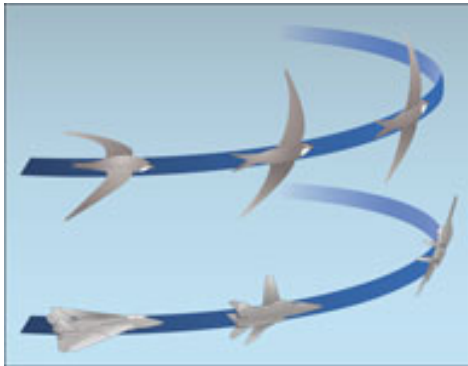


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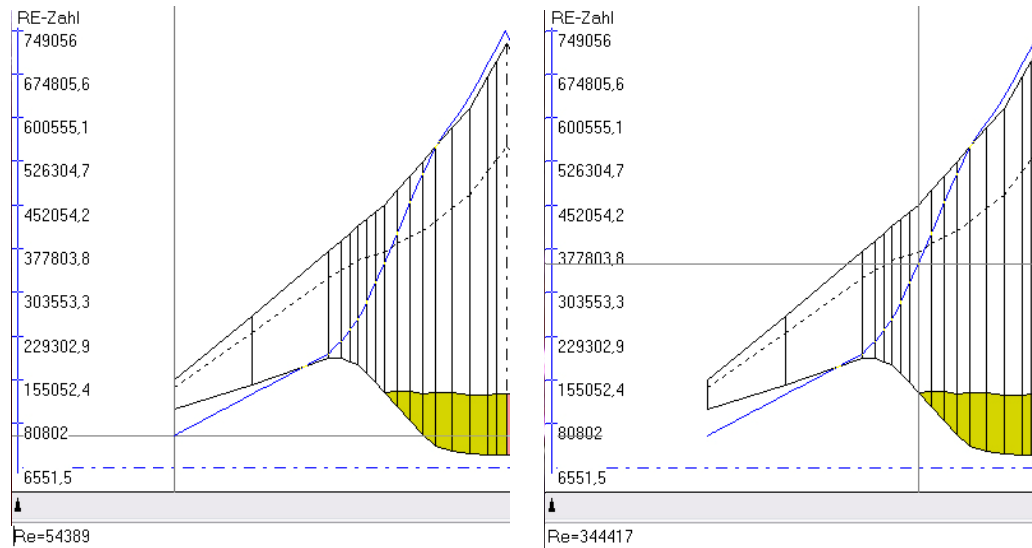
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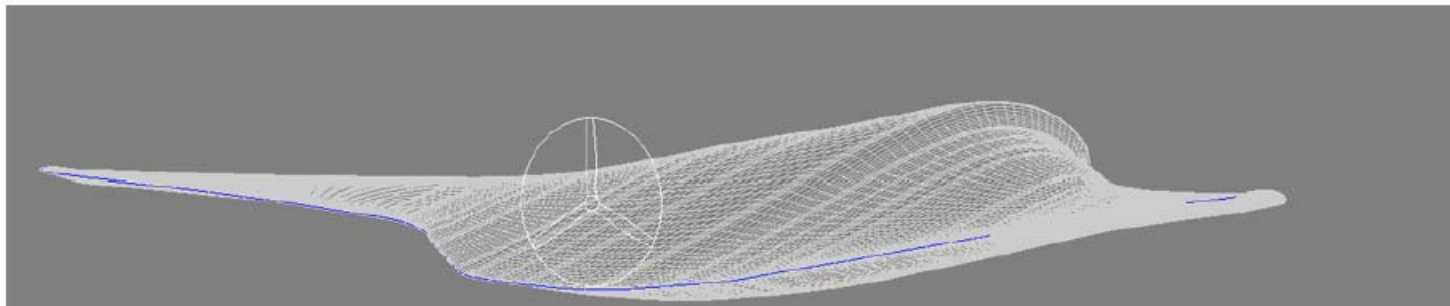
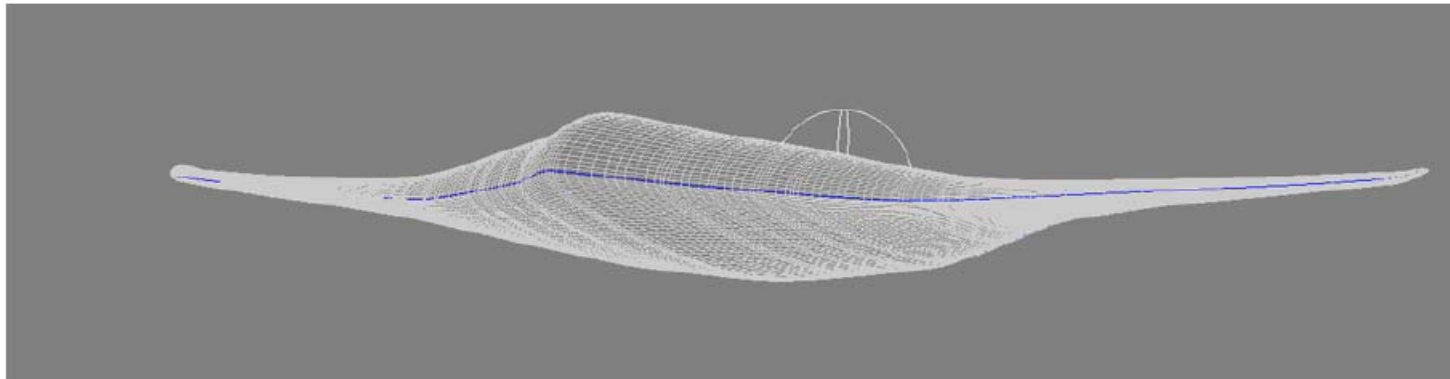
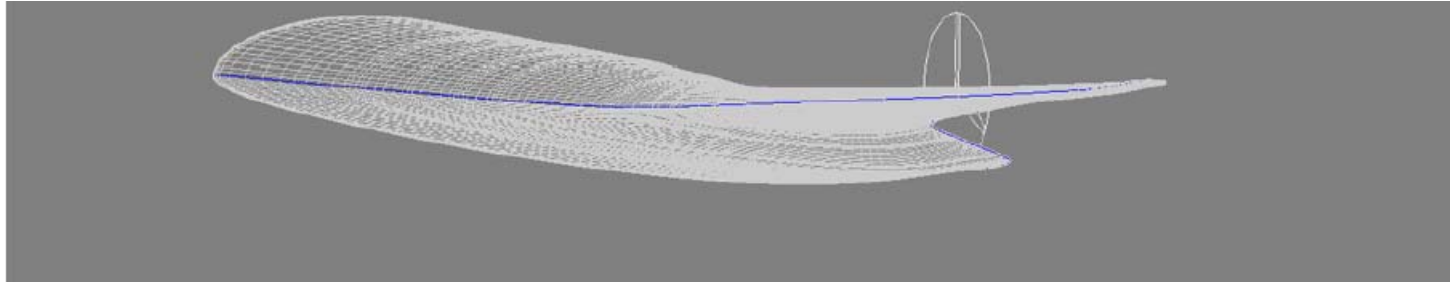
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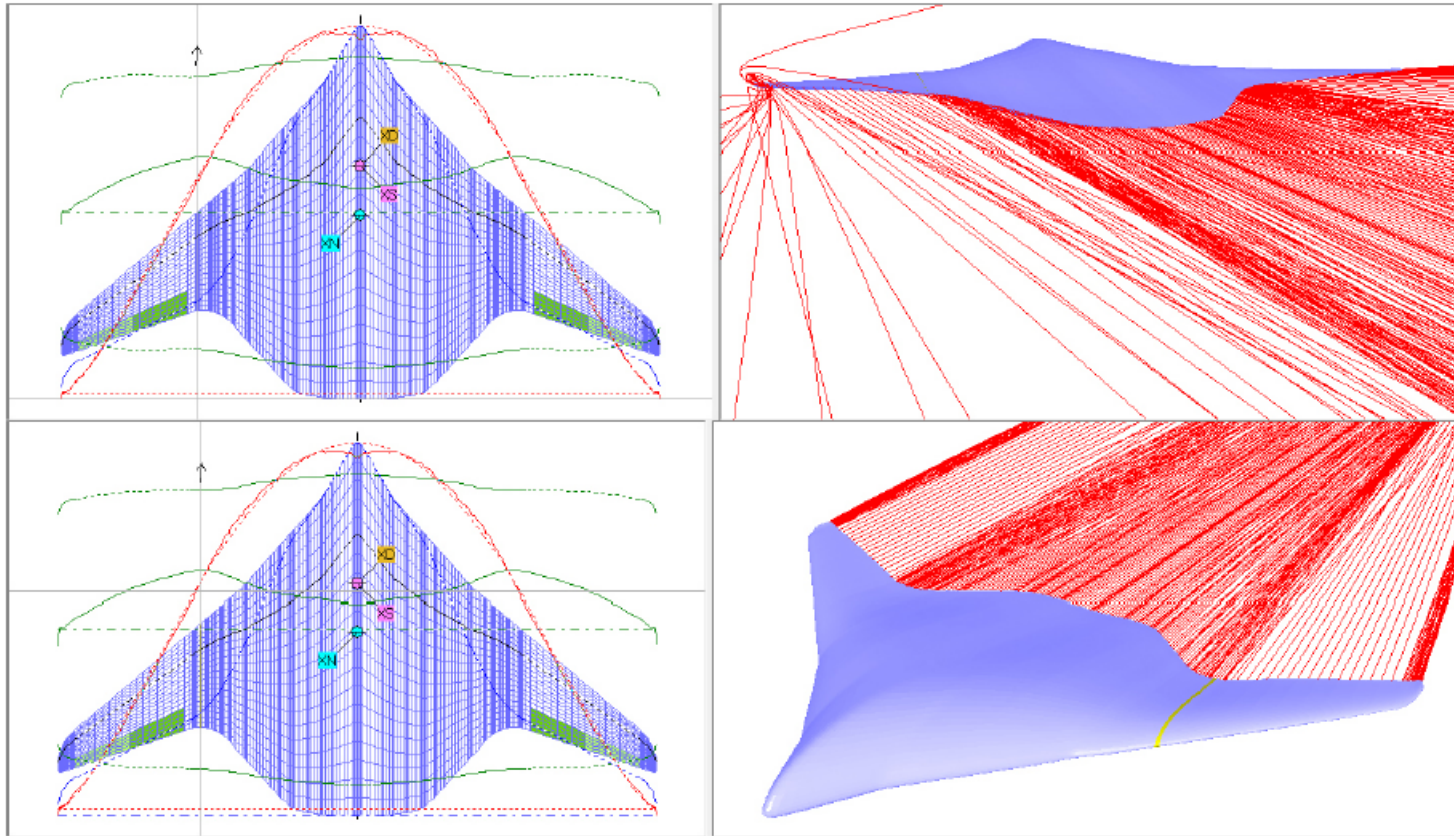
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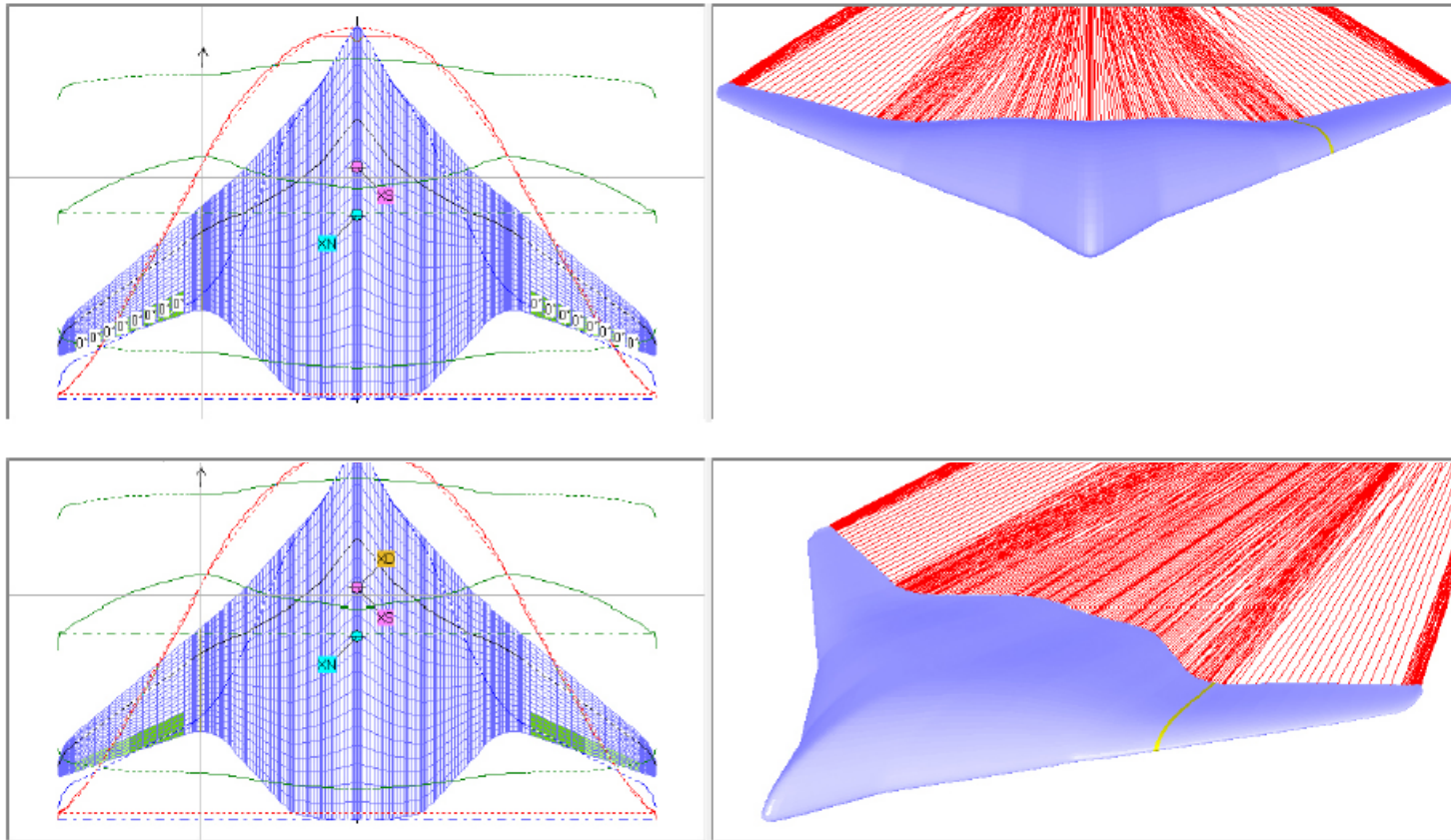
Multi DBD Plasma Mini UAV with 180 cm Span Width and 4.99 kg Weight



Multi DBD Plasma Mini UAV with 180 cm Span Width and 4.99 kg Weight



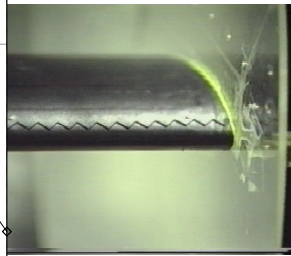
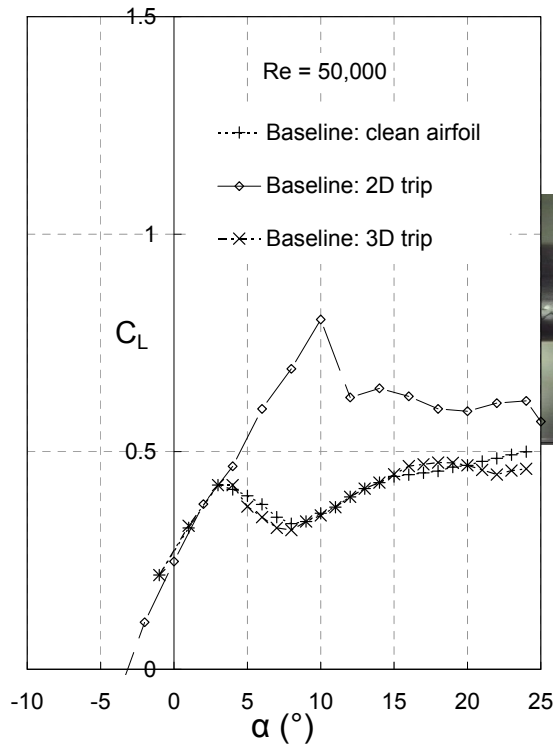
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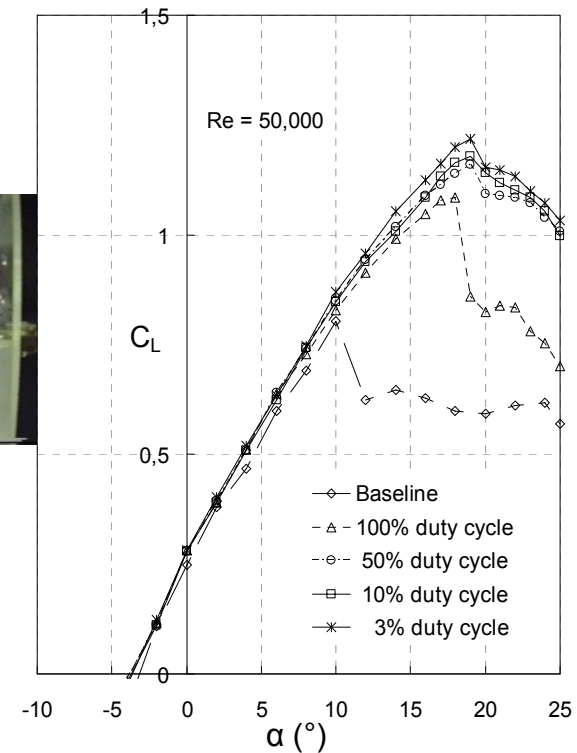
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Dielectric Barrier Discharge Plasma: 8 – 10 kVpp, 0.2 – 5.0 W

Boundary Layer Tripping

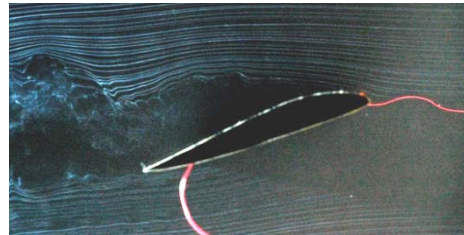


Boundary Layer Control with Plasma Actuator

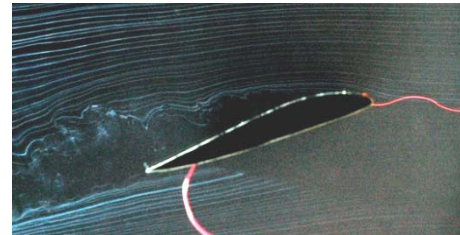


Example of the effect of boundary layer tripping and plasma actuation at $F^+=1$ on airfoil performance at Reynolds number $Re=50,000$.

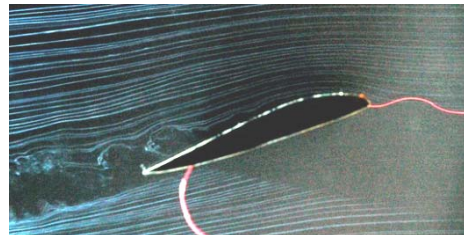
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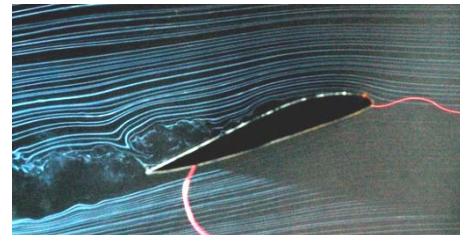
(a) 0% duty cycle (0kVpp)



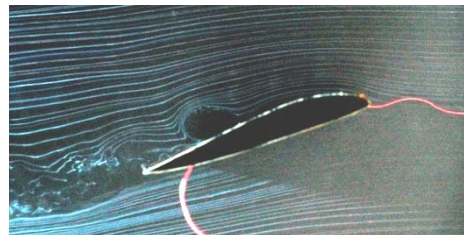
(b) 100% duty cycle



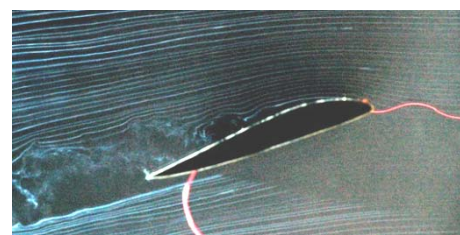
(c) 50% duty cycle ($F^+=1$)



(d) 10% duty cycle ($F^+=1$)

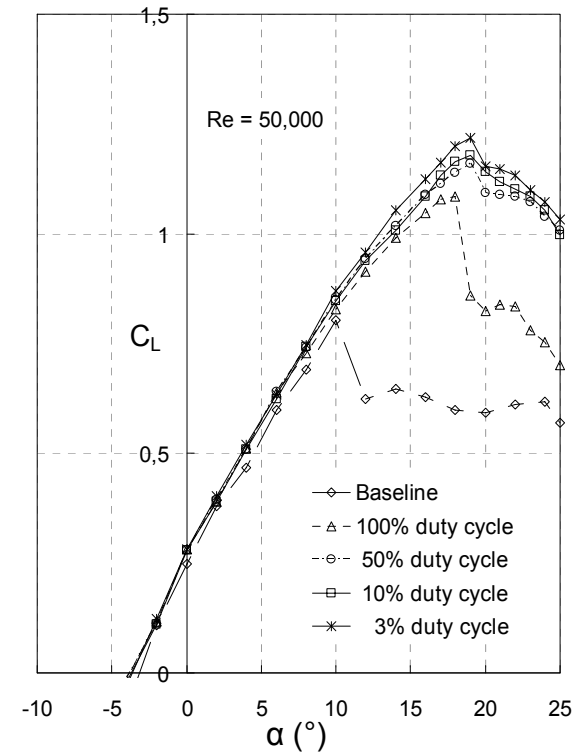


(e) 3% duty cycle ($F^+=1$)



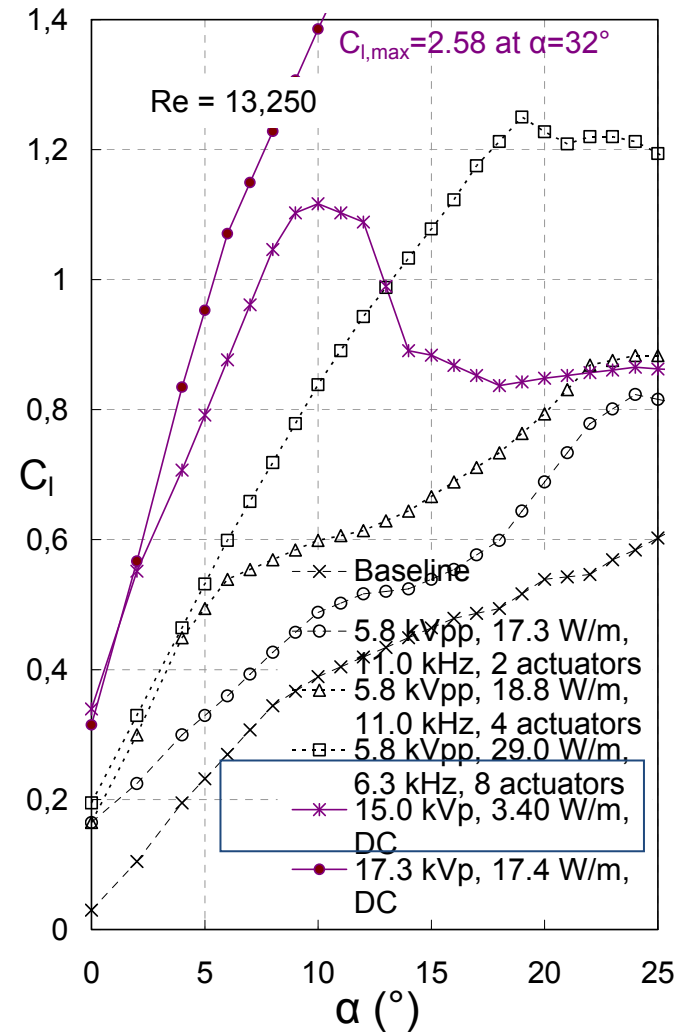
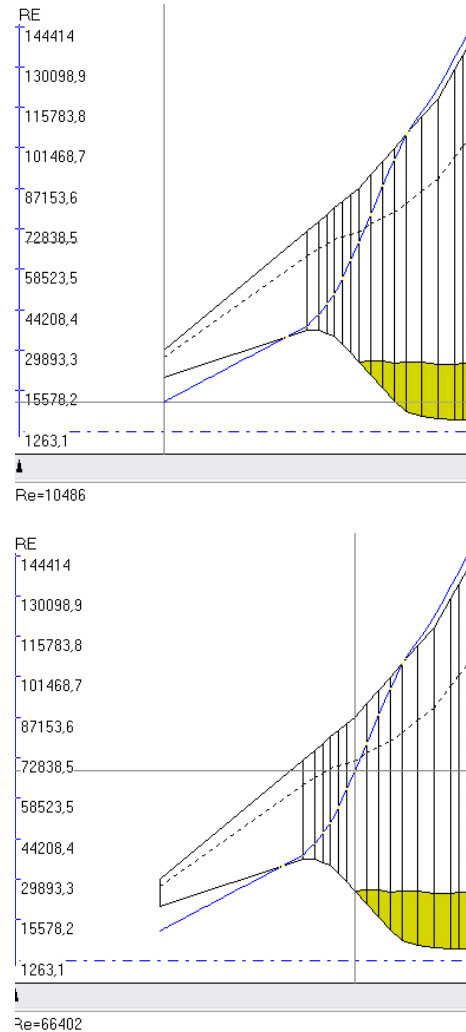
(f) 1% duty cycle ($F^+=1$)

Boundary Layer Control with Plasma Actuator



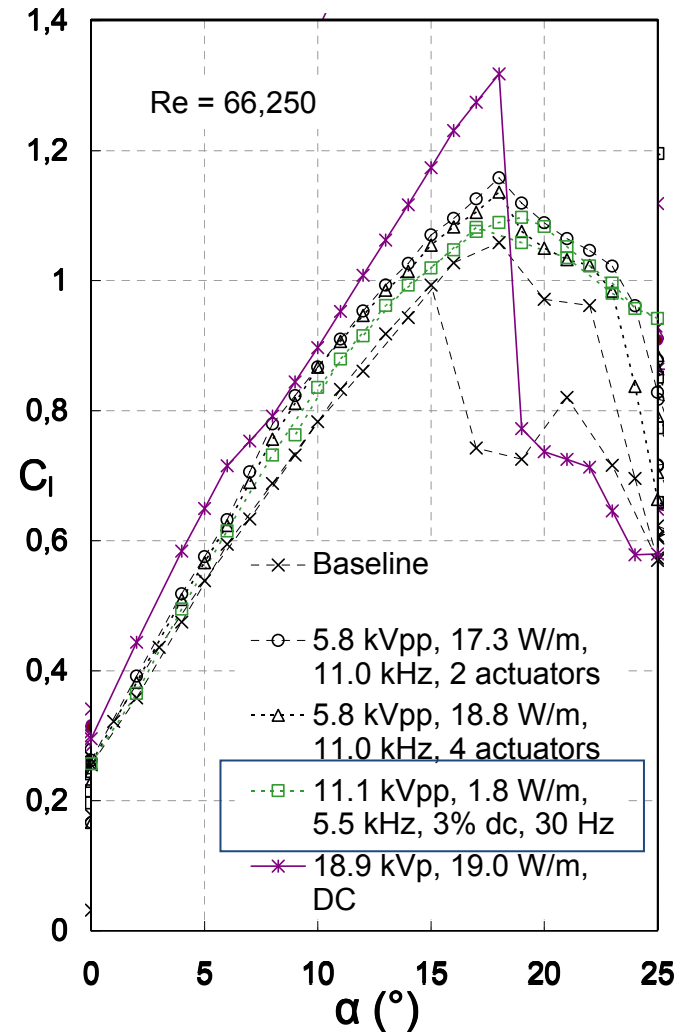
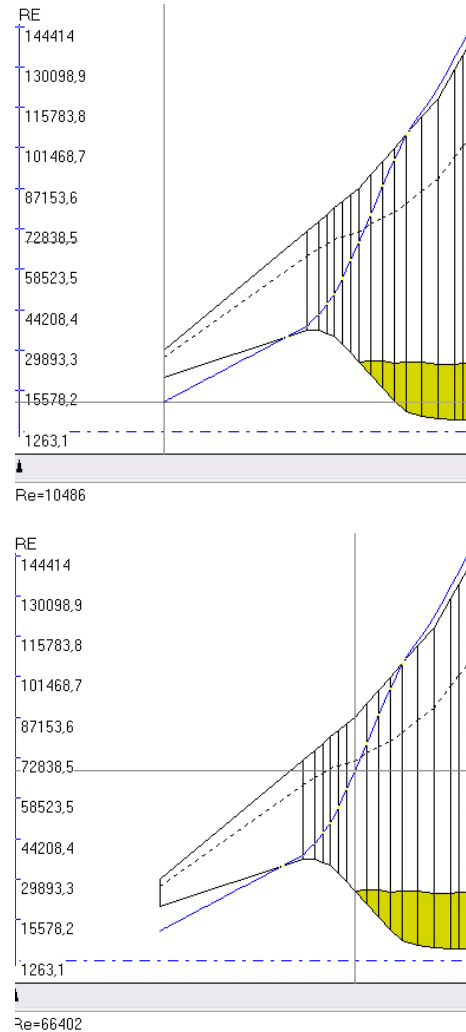
Multi Dielectric Barrier Discharge Plasma: 4 – 6 kVpp, 5 – 30 W

30 cm MAV



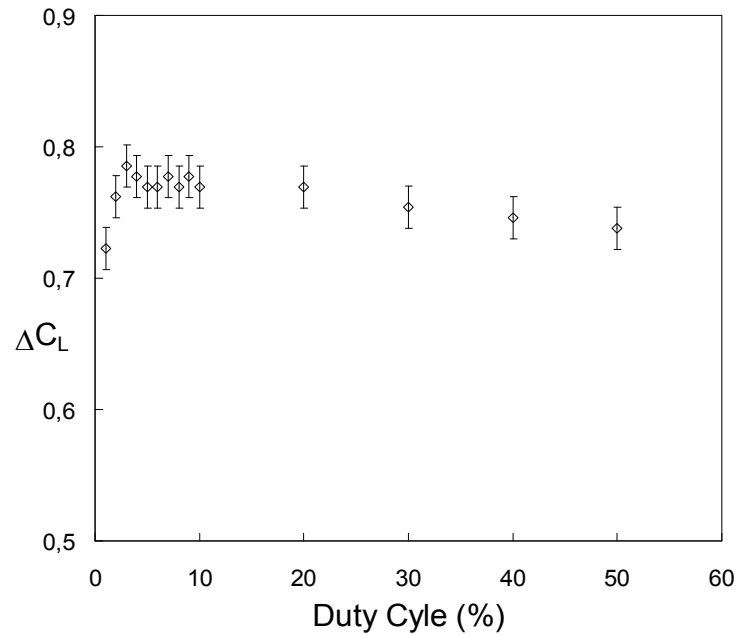
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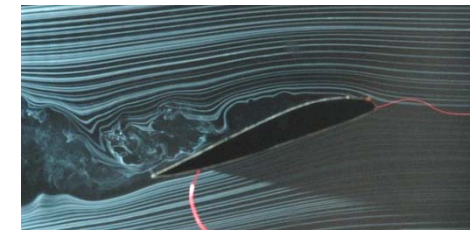
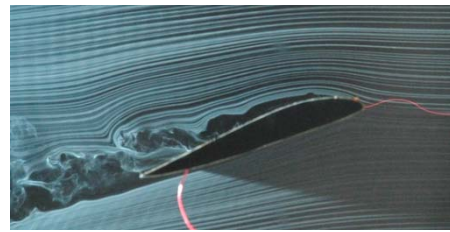
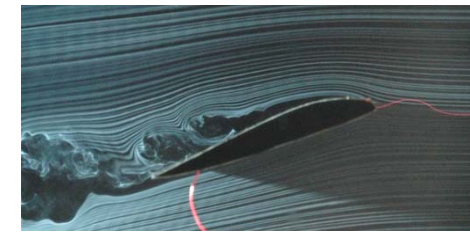
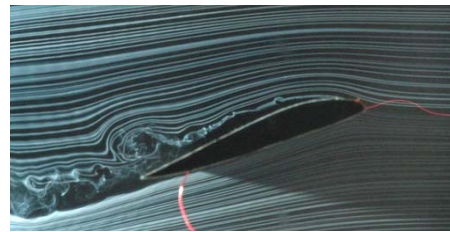
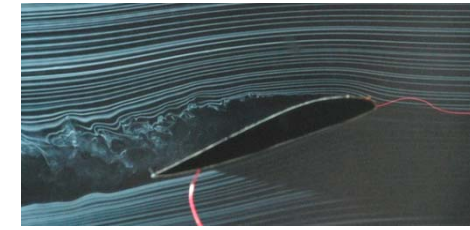
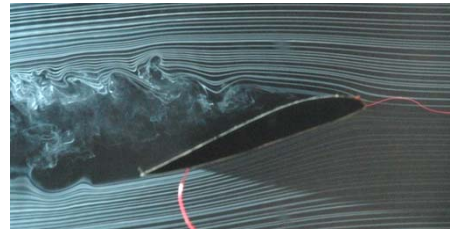


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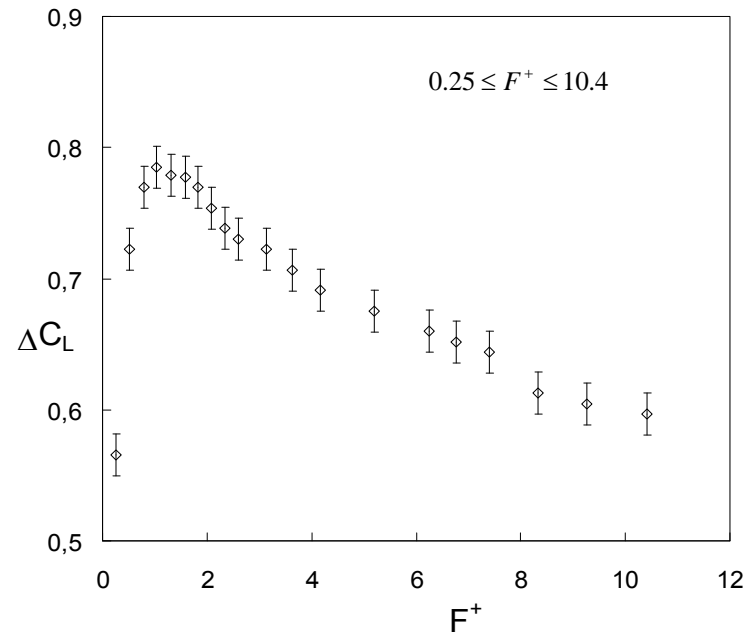
Smoke Wire Flow Visualization at $Re=20,500$ ($F^+=1 \rightarrow f=9.6$ Hz)



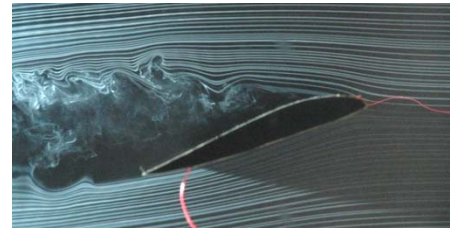
Effect of duty cycle on post-stall ($\alpha=18^\circ$ airfoil lift at a low MAV Reynolds number; $Re=20,500$).



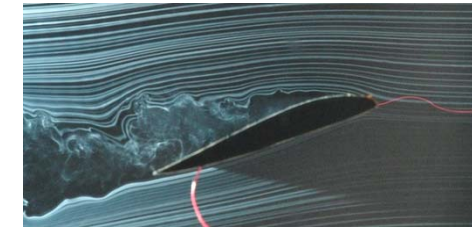
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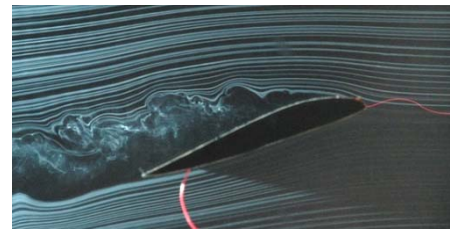
Effect of Strouhal number on post-stall ($\alpha=18^\circ$ airfoil lift at a low MAV Reynolds number; $Re=20,500$). $C_{\mu}=0.05\%$ and duty cycle = 3%.



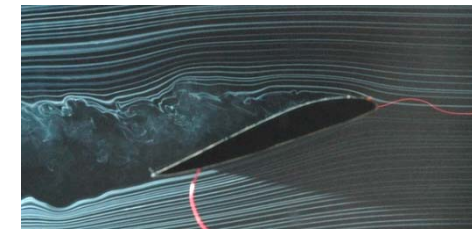
(a) 0% duty cycle ($F^+=0$)



(b) 3% duty cycle ($F^+=1$)



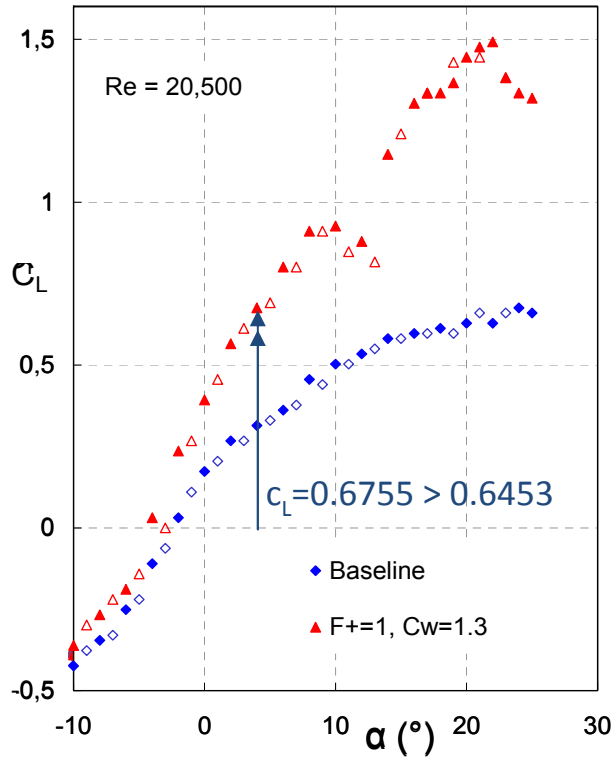
(c) 3% duty cycle ($F^+=2$)



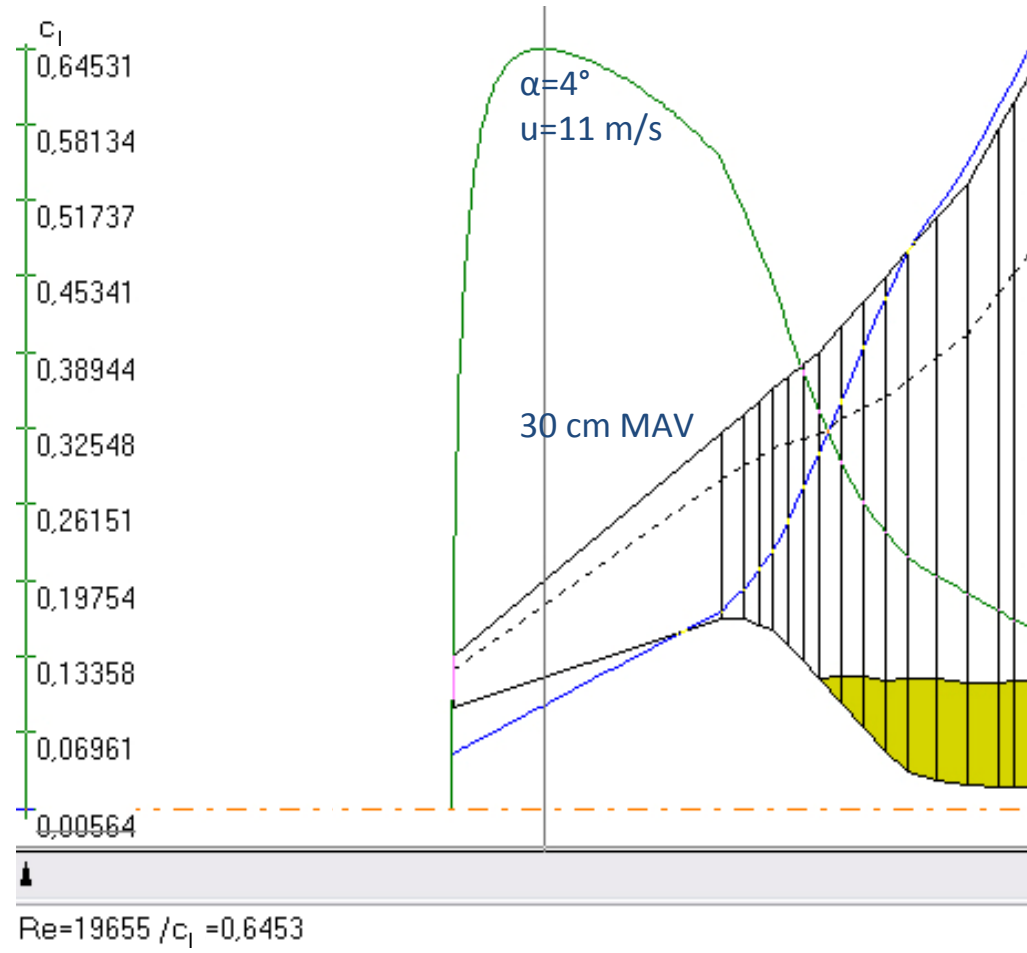
(d) 3% duty cycle ($F^+=3$)

Examples of flow visualization photographs at different reduced frequencies for $\alpha=18^\circ$ at $Re=20,500$ without and with the plasma actuator on. Larger lift is generally associated with larger downward deflection of the streamlines. Here it can be seen that the greatest deflections occur at $F^+=1$ and that the wakes associated with higher frequencies are larger.

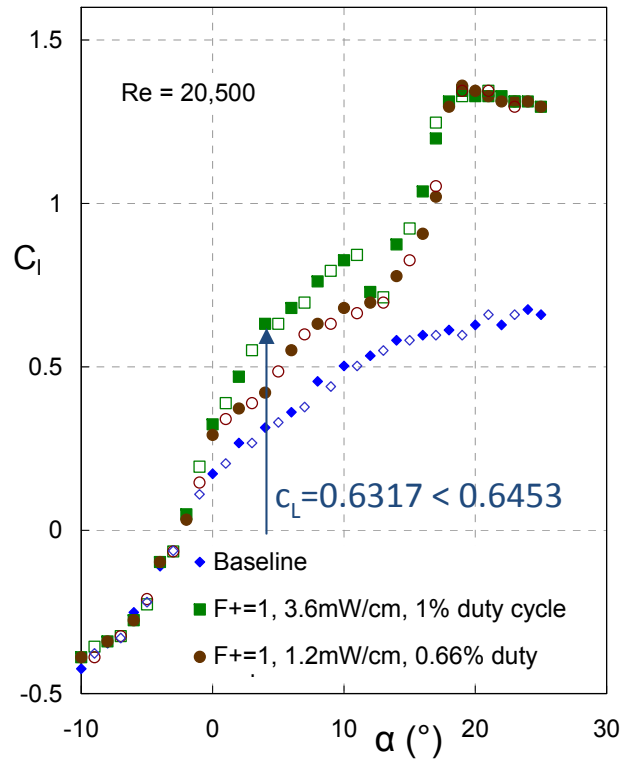
Smoke Wire Flow Visualization at $Re=20,500$ ($F+=1 \rightarrow f=9.6$ Hz)



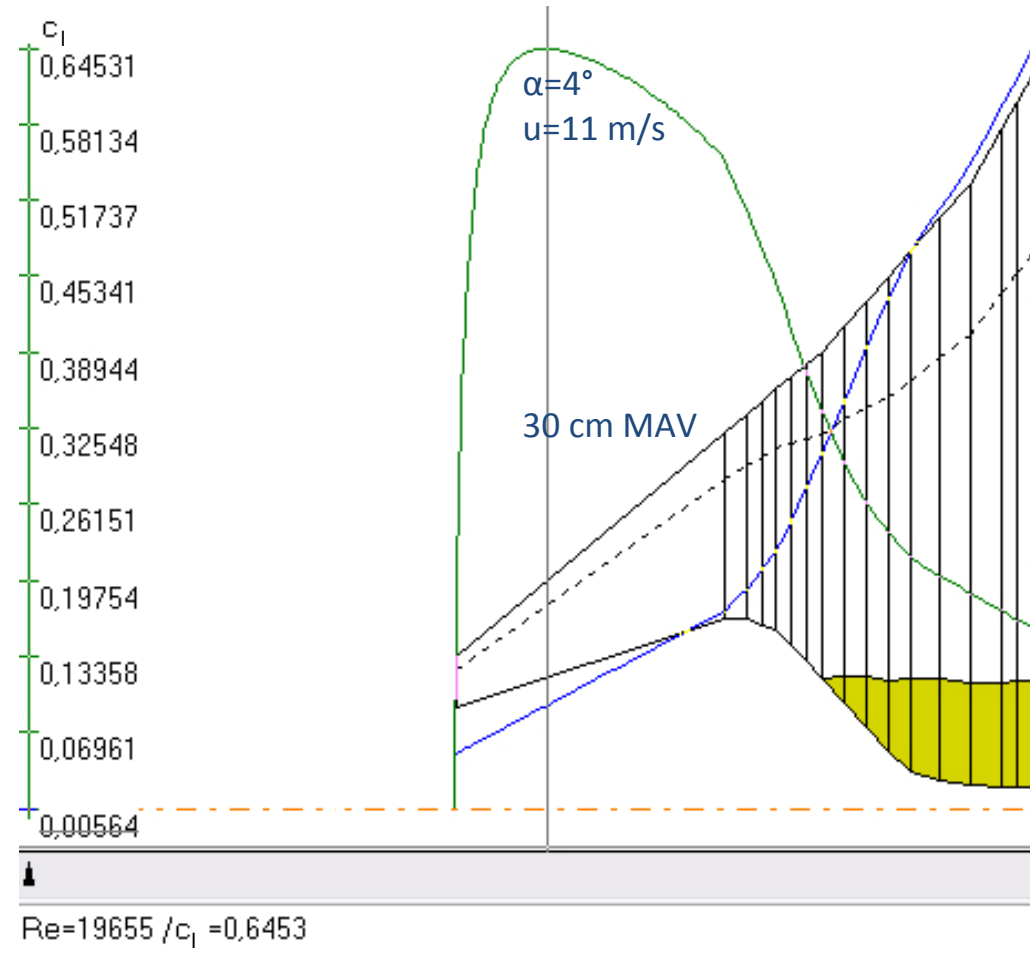
Effect of plasma actuation (8kVpp with 5mW/cm and 10kVpp with 9mW/cm or 0.9W/m at 4kHz), duty cycle = 3%.



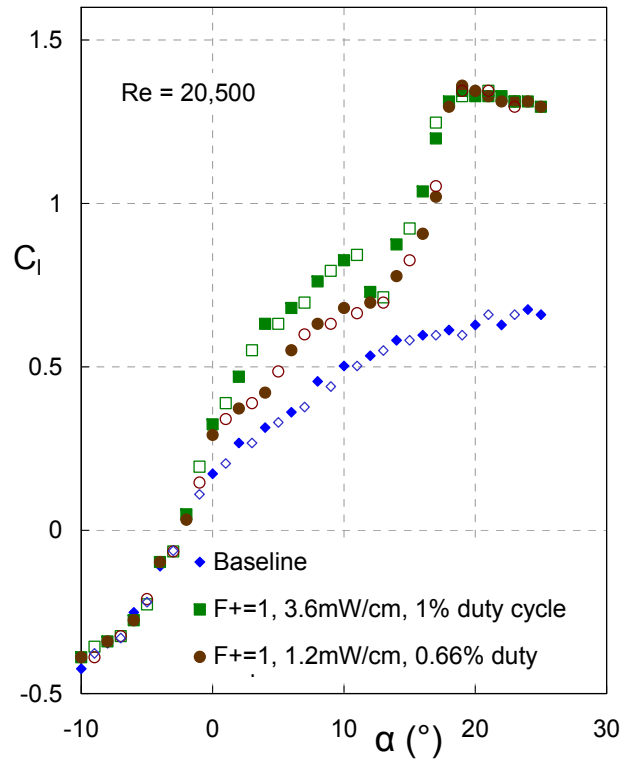
Smoke Wire Flow Visualization at $Re=20,500$ ($F+=1 \rightarrow f=9.6$ Hz)



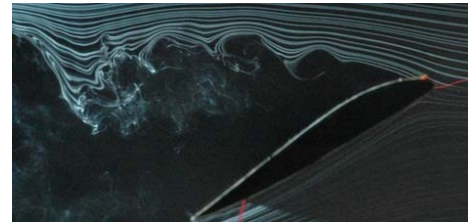
Effect of plasma actuation (10kVpp with 3.6mW/cm and 9kVpp with 1.2mW/cm at 4kHz), duty cycle = 0.66%.



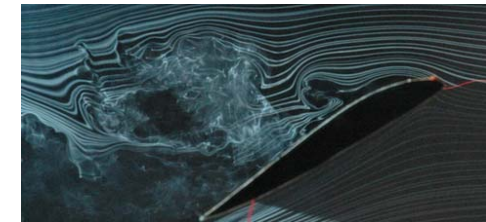
Smoke Wire Flow Visualization at $Re=20,500$ ($F+=1 \rightarrow f=9.6$ Hz)



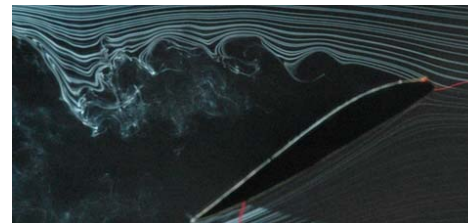
Effect of plasma actuation (10kVpp with 3.6mW/cm and 9kVpp with 1.2mW/cm at 4kHz), duty cycle = 0.66%.



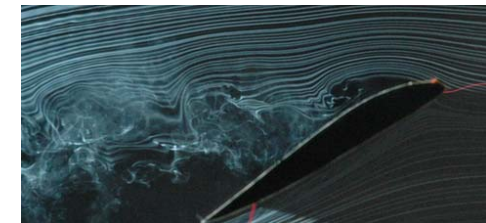
(a) 0% duty cycle ($F+=0$) ($\alpha=18^\circ$)



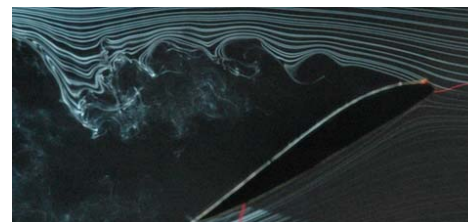
(b) 0.66% duty cycle ($F+=1$) ($\alpha=18^\circ$)



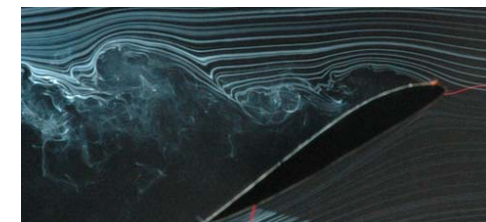
(c) 0% duty cycle ($F+=0$) ($\alpha=18^\circ$)



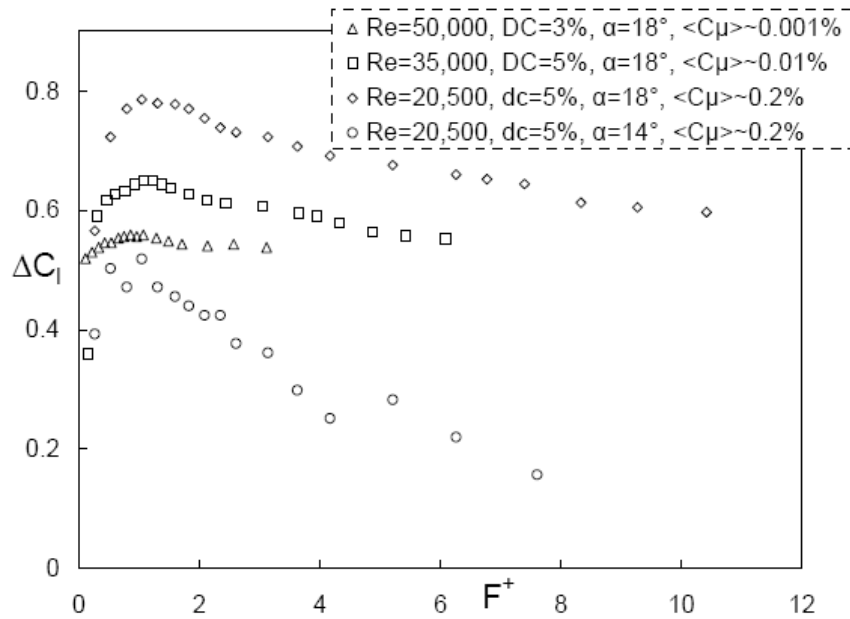
(d) 0.21% duty cycle ($F+=1$) ($\alpha=18^\circ$)



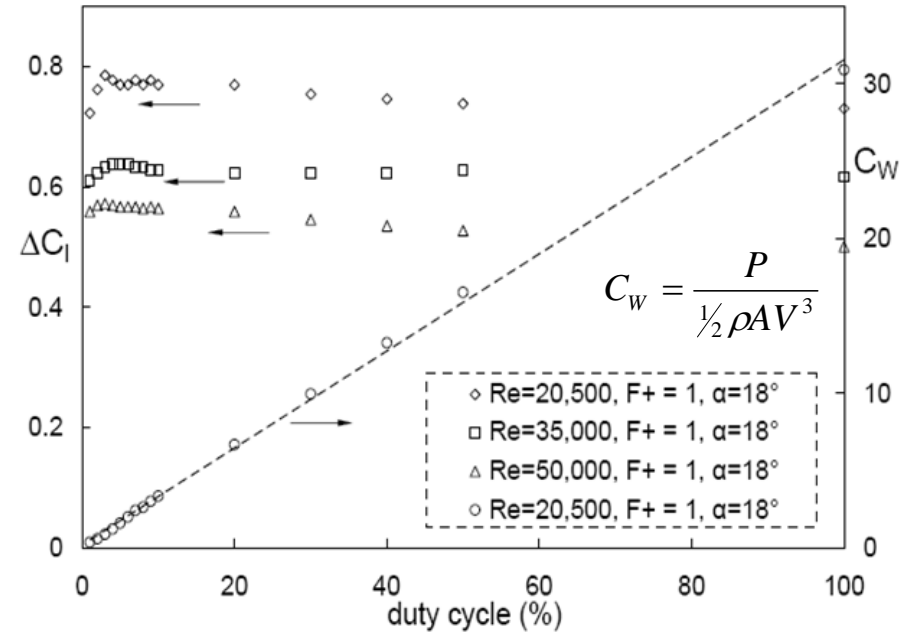
(e) 0% duty cycle ($F+=0$) ($\alpha=30^\circ$)



(f) 0.21% duty cycle ($F+=1$) ($\alpha=30^\circ$)



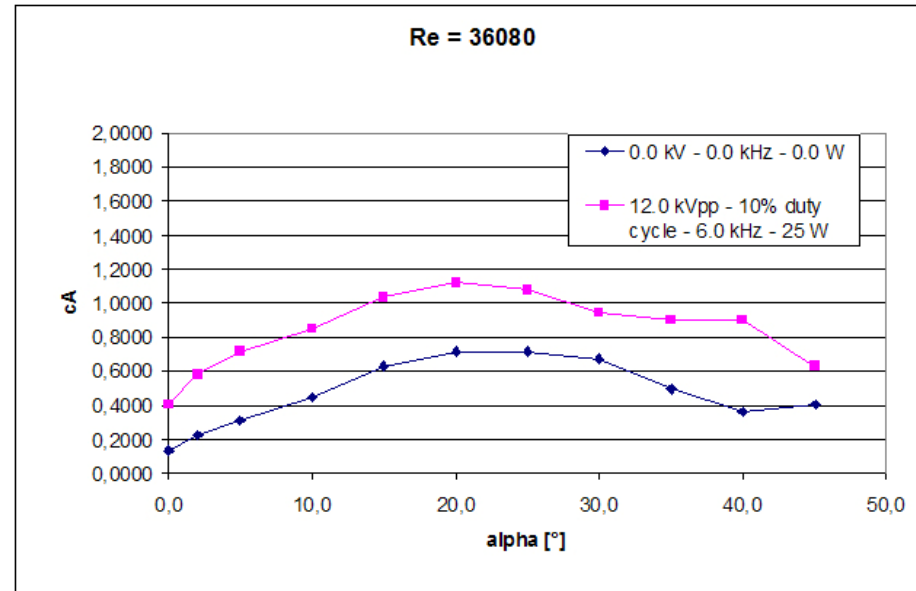
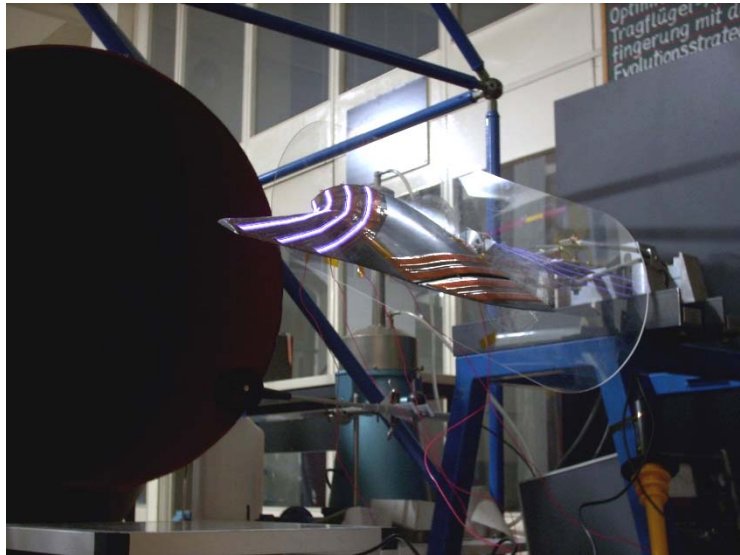
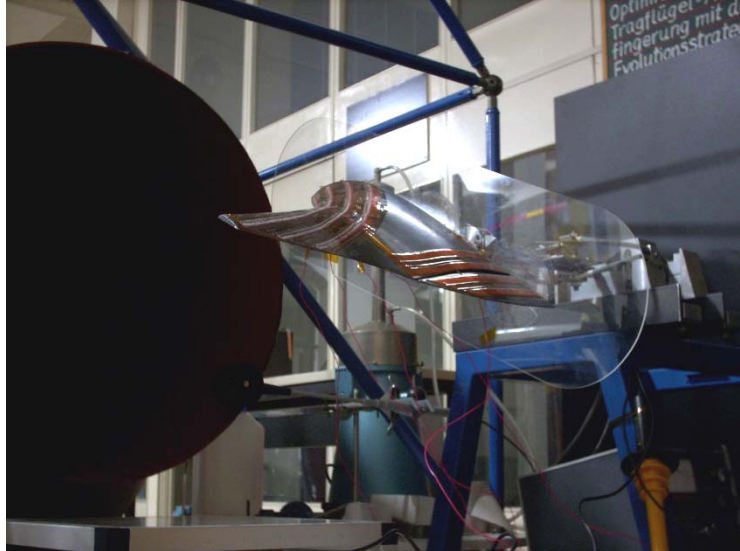
Effect of reduced frequency on post-stall airfoil lift at different Reynolds numbers. Plasma at 10kVpp and 4kHz.



Effect of duty cycle on post-stall airfoil lift with plasma at 10kVpp and 4kHz for various Reynolds numbers. Corresponding measured power coefficient for Re=20,500.

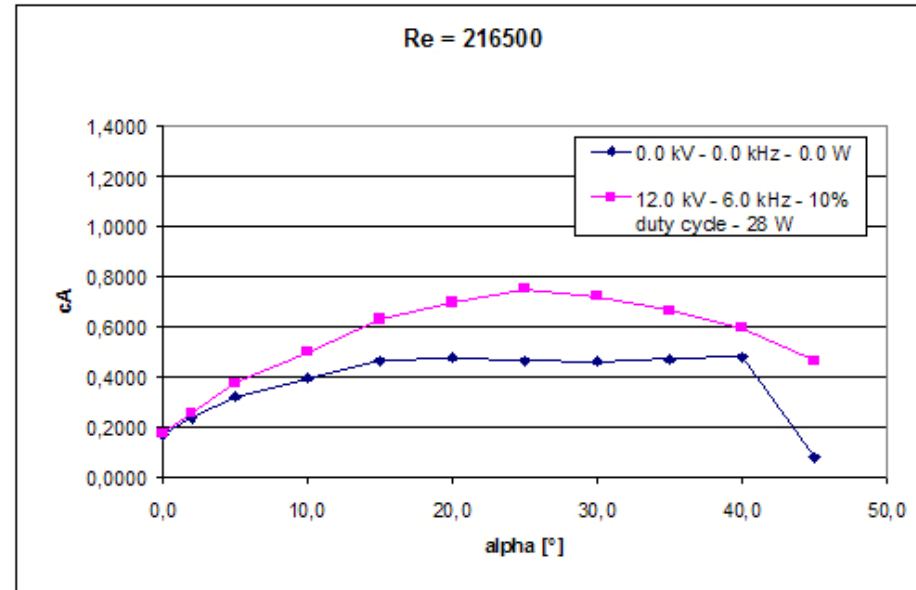
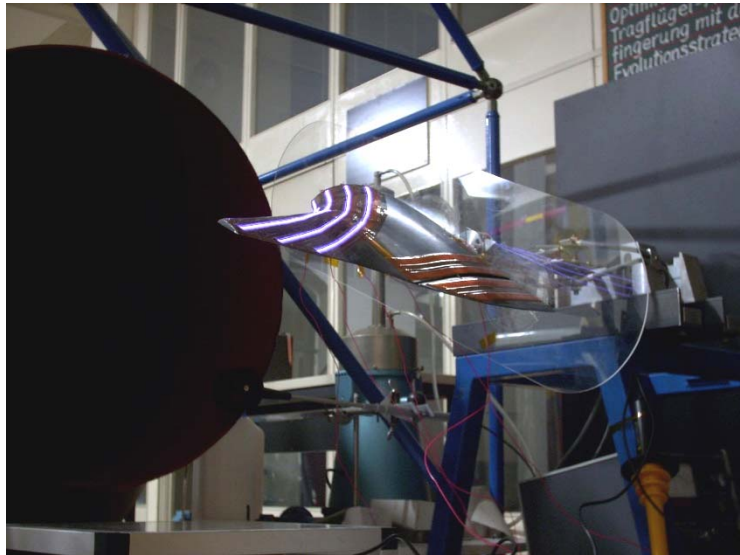
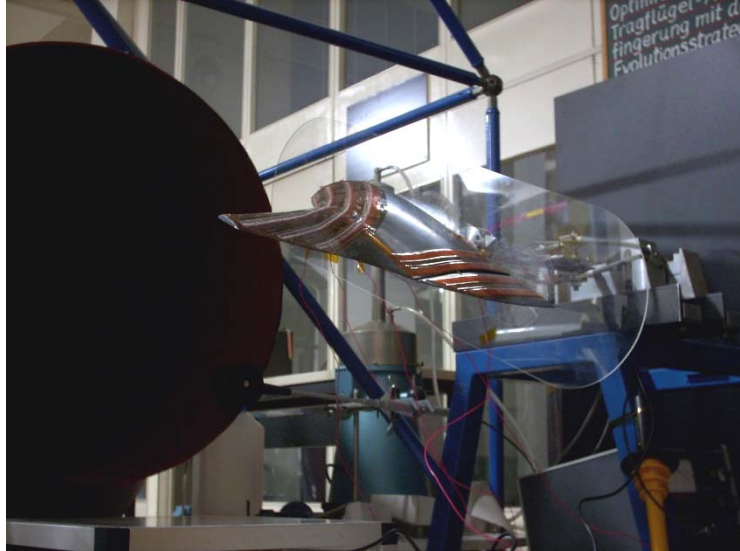
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 - Flying Wing Half Models
 - Flying Wing Flight Models
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 - Airfoil Performance
 - Optimization Study
 - **Half Wing Performance**
- Conclusions and Outlook

Half Wing Performance



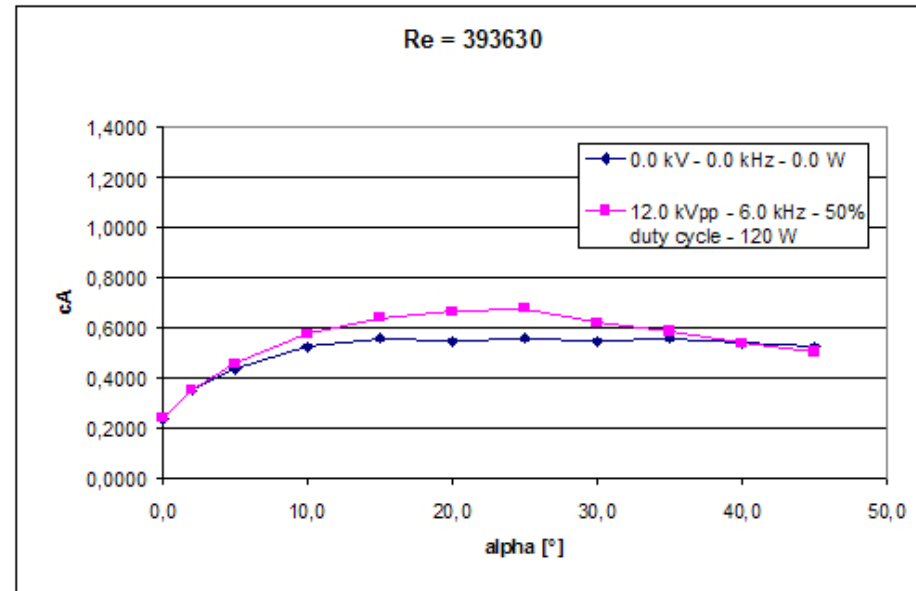
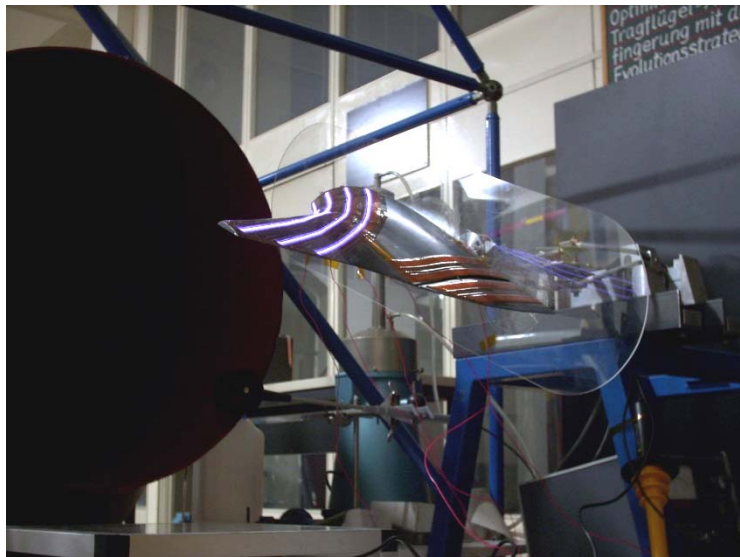
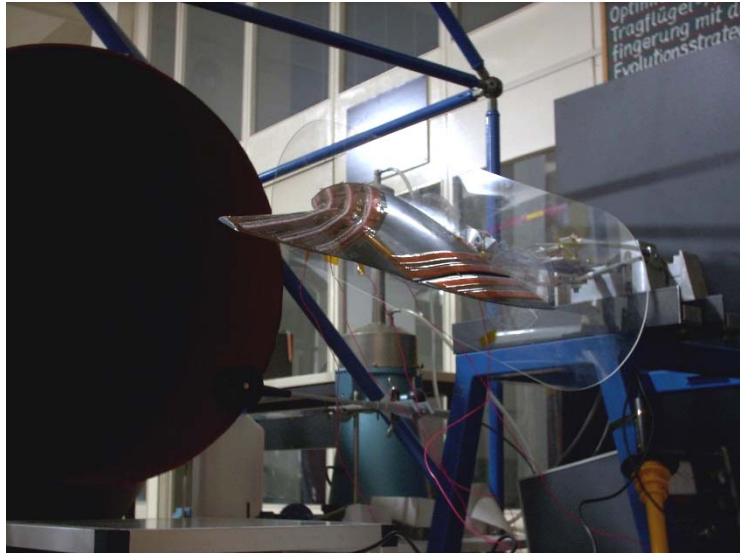
Effect of phased plasma array with four leading edge actuators on half-span wing performance at a root Reynolds number (a) $Re=36,080$ (lift enhanced by max. 300%), (b) $Re=216,000$ (here by max. 60%) and (c) $Re=393,000$ (here by max. 25%)

Half Wing Performance



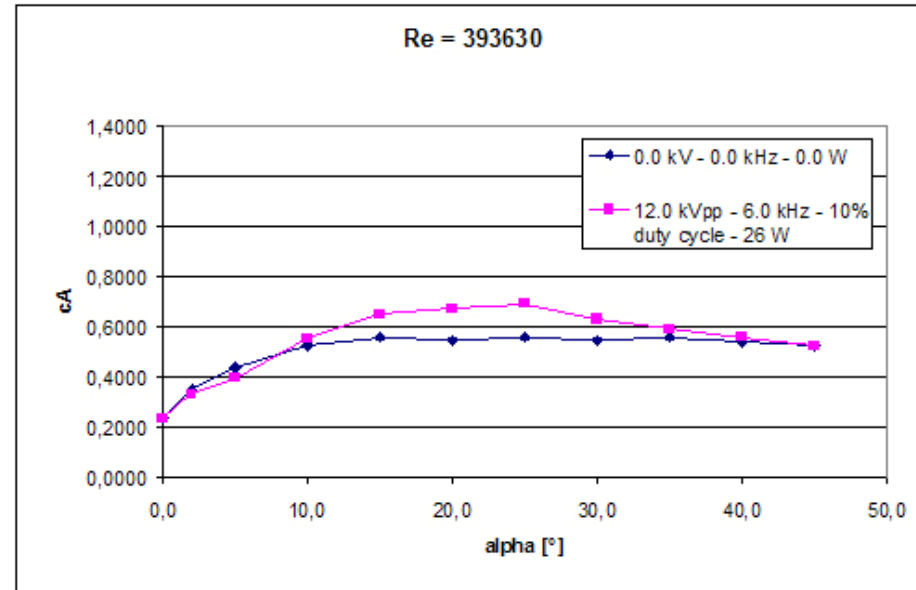
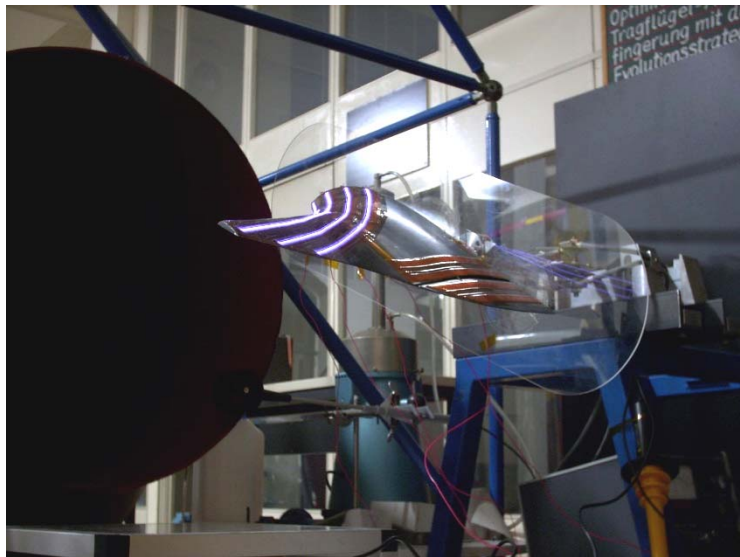
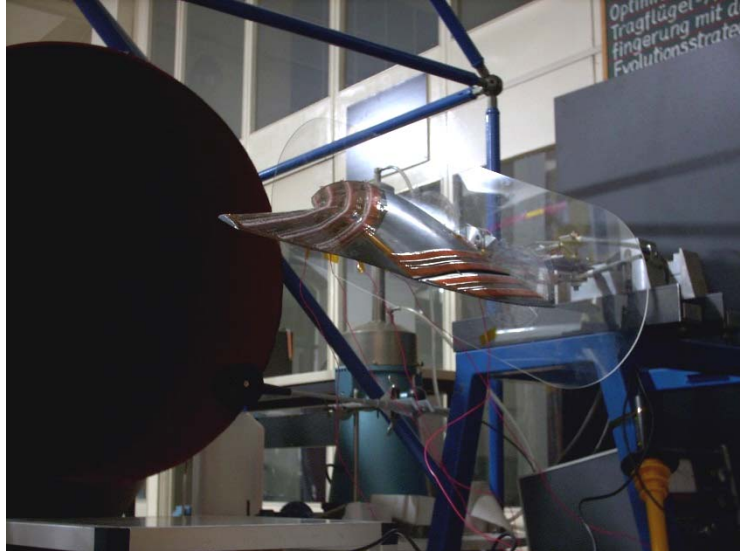
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Half Wing Performance



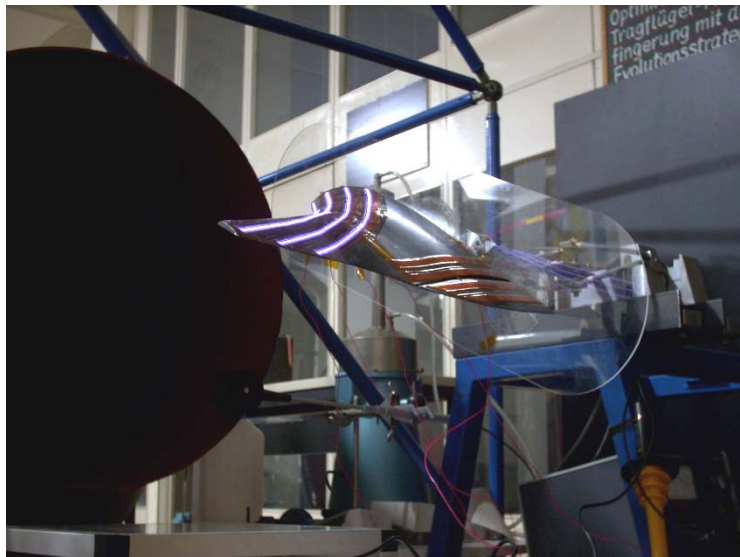
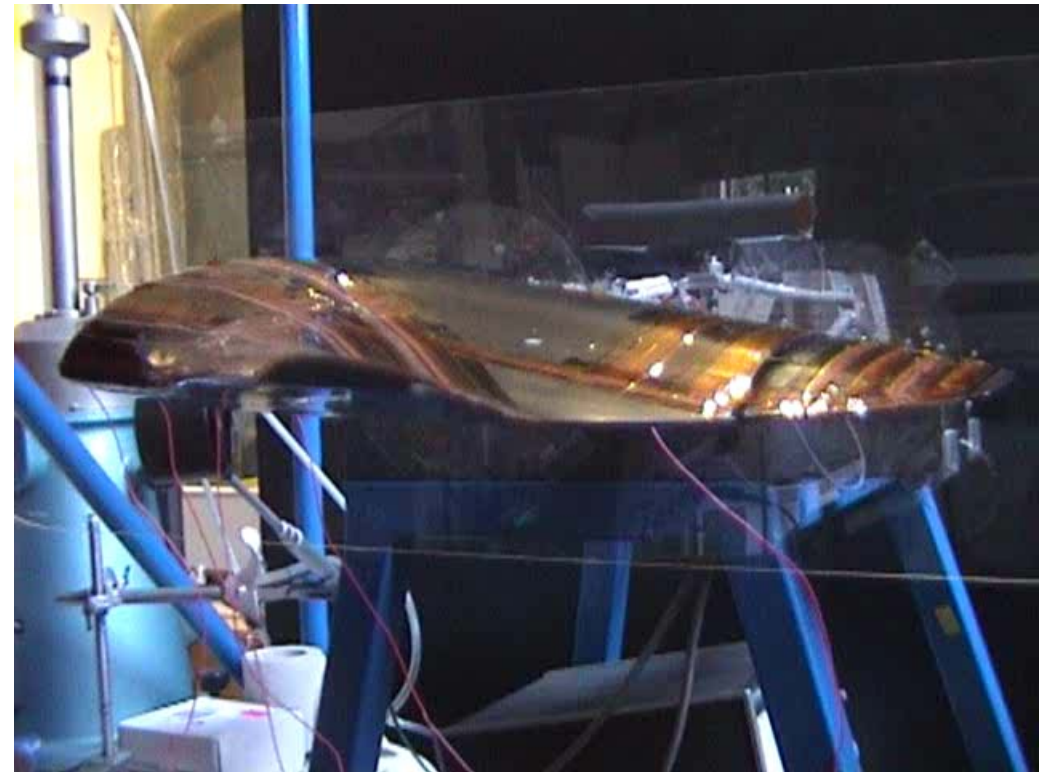
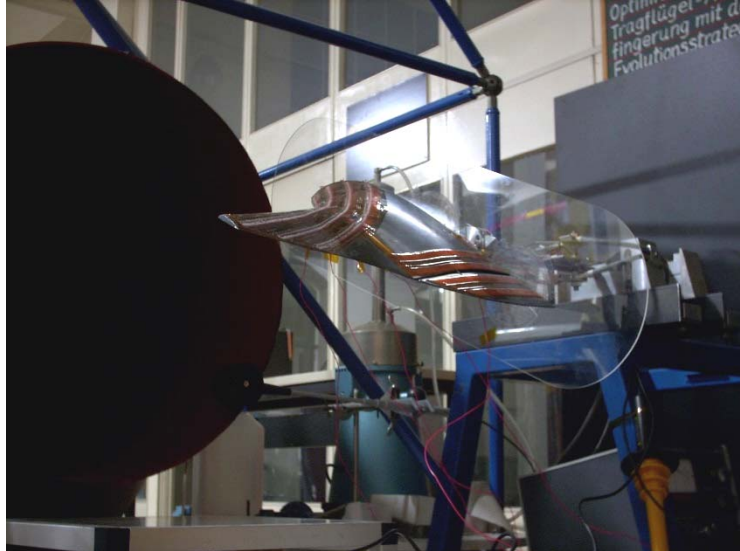
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Half Wing Performance



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Half Wing Performance

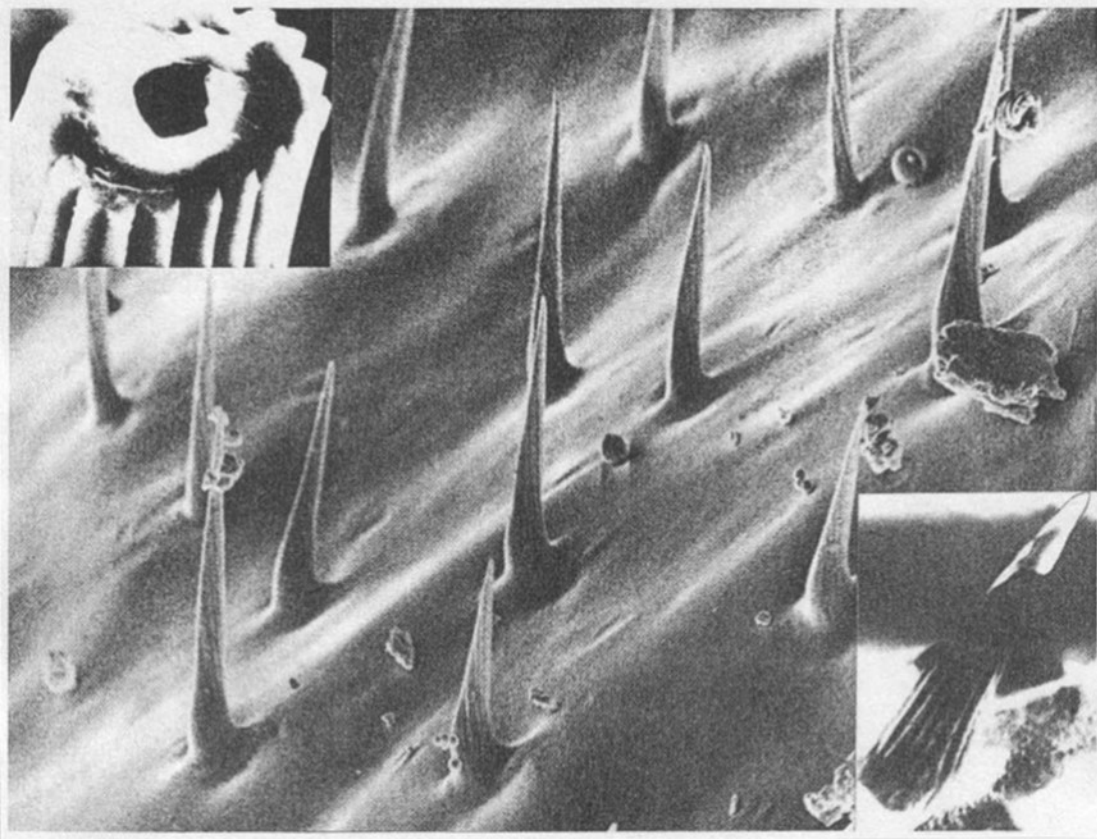


Effect of phased plasma array with four leading edge actuators on half-span wing performance at a root Reynolds number (a) $Re=36,080$ (lift enhanced by max. 300%), (b) $Re=216,000$ (here by max. 60%) and (c) $Re=393,000$ (here by max. 25%)

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- The present investigation considered separation control using single and multi dielectric barrier discharge actuation on an airfoil and half wing models at typical MAV Reynolds numbers.
- Modulating the dielectric barrier discharge actuators at frequencies corresponding to $F^+ \approx 1$, resulted in improvements to $C_{l,max}$, which increased with reductions in Re . At the low end of the MAV Reynolds number range ($Re=20,500$) modulation increased $C_{l,max}$ by more than a factor of 2. Hysteresis associated with the baseline airfoil was eliminated.
- Of particular interest from an applications perspective was that performance, measured here by $C_{l,max}$, increased with decreasing duty cycle, and hence power input, for duty cycles $\geq 3\%$. Even lower duty cycles, around 0.66%, were sufficient for effective separation control, corresponding to power inputs on the order of 1.2 milliwatts per centimeter.
- In ongoing experiments, the positive aspects of corona and dielectric barrier discharge plasma actuators are combined in so-called sliding discharge actuators to increase the aerodynamic efficiency of small MAV designs.
- Plasma actuators should also be studied in combination with flapping wing configurations. Why?

Strange Topography of Bee Wings - Sensors or Supporting Electrokinetic Actuators ?



Warnke, U. (1979) Information Transmission by Means of Electrical Biofields. In *Electromagnetic Bio-Information*, Eds. Popp, F.-A.; Peschka, W., Verlag Urban und Schwarzenberg, München, pp. 55-79.

Stuetzer, O. M. (1961) Apparent Viscosity of a Charged Fluid. *Phys. Fluid* **4** (10), pp. 1226-1231.

Stuetzer, O. M. (1962) Magnetohydrodynamics and Electrohydrodynamics. *Phys. Fluid* **5** (5), pp. 534-544.

Stuetzer, O. M. (1963) *Electrohydrodynamic flow control*. SC-M-69-366, Sandia Corporation, Albuquerque, New Mexico.

Velkoff, H. R. (1962) *Electrofluidmechanics: A Study of Electrokinetic Actions in Fluids*. ASD-TR-61-642. Propulsion Laboratory, Wright-Patterson AFB, Ohio.

What is the Electrokinetic Effect on Vortex Viscosity at Low Reynolds Numbers?

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Thank you for your attention!
Any questions?

